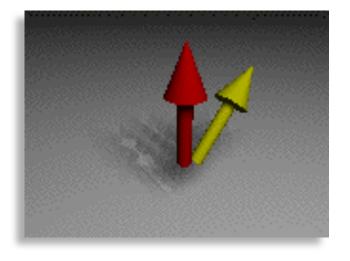
## Neutron Spin Echo Spectroscopy



Peter Fouquet fouquet@ill.eu



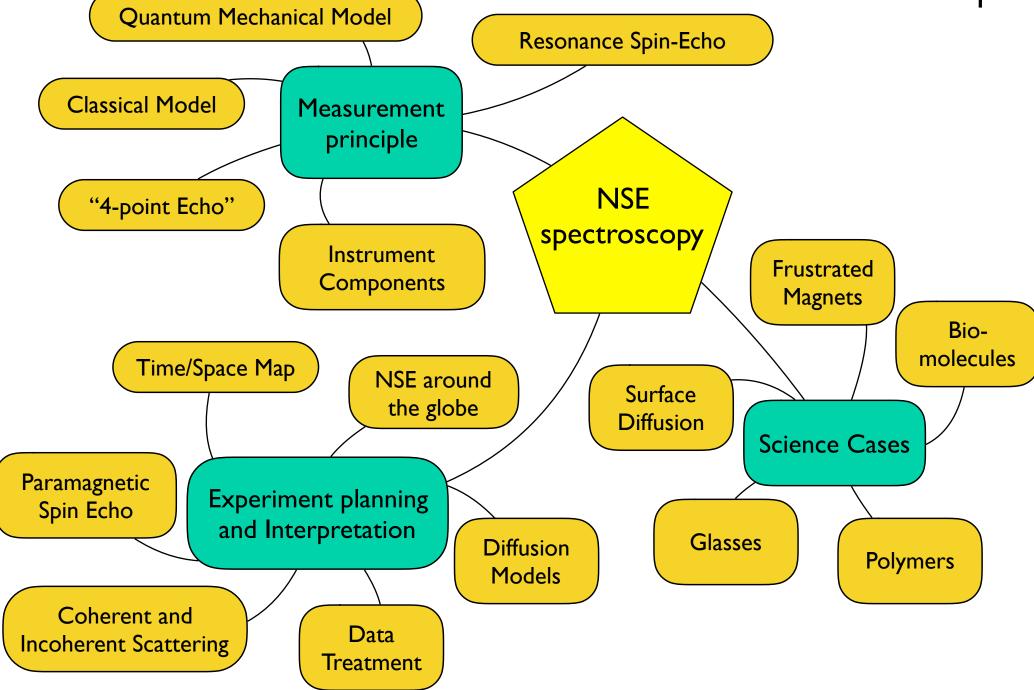
Institut Laue-Langevin Grenoble, France

Oxford Neutron School 2017

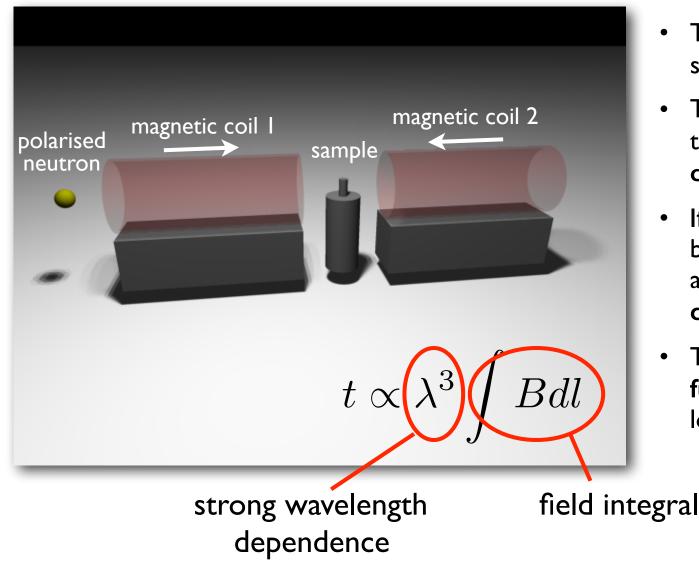
## What you are supposed to learn in this tutorial

- I. The length and time scales that can be studied using NSE spectroscopy
- 2. The measurement principle of NSE spectroscopy
- 3. Discrimination techniques for coherent, incoherent and magnetic dynamics
- 4. To <u>which scientific problems</u> can I apply NSE spectroscopy?

## **NSE-Tutorial Mind Map**

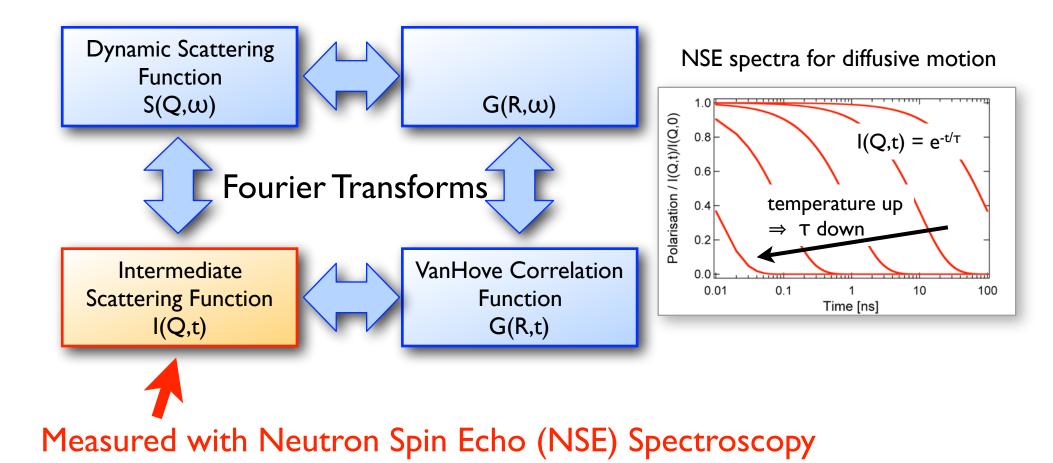


## <u>The measurement principle of neutron spin echo spectroscopy</u> (quantum mechanical model)

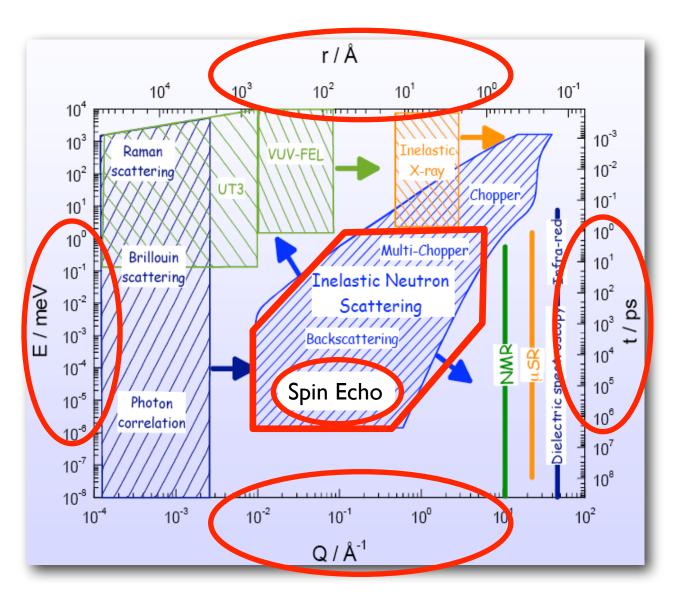


- The neutron wave function is split by magnetic fields
- The 2 wave packets arrive at the sample with a time difference t
- If the molecules move between the arrival of the first and second wave packet then coherence is lost
- The intermediate scattering function I(Q,t) reflects this loss in coherence

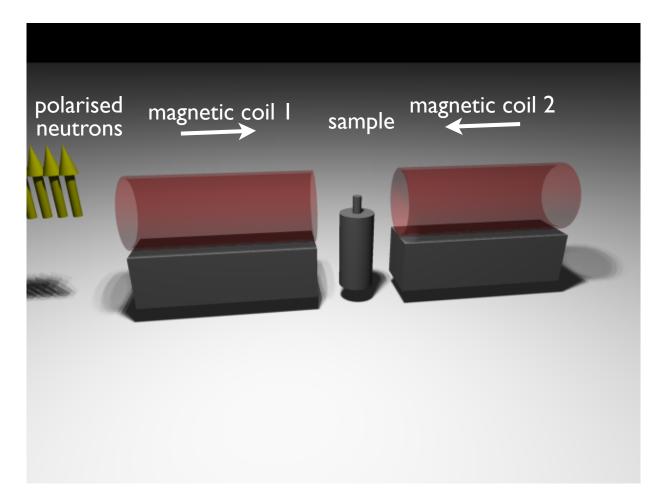
### The measurement principle of neutron spin echo spectroscopy



### Neutron spin echo spectroscopy in the time/space landscape



- NSE is the neutron spectroscopy with the highest energy resolution
- The time range covered is
  I ps < t < I μs (equivalent to neV energy resolution)</li>
- The momentum transfer range is 0.01 < Q < 4 Å<sup>-1</sup>

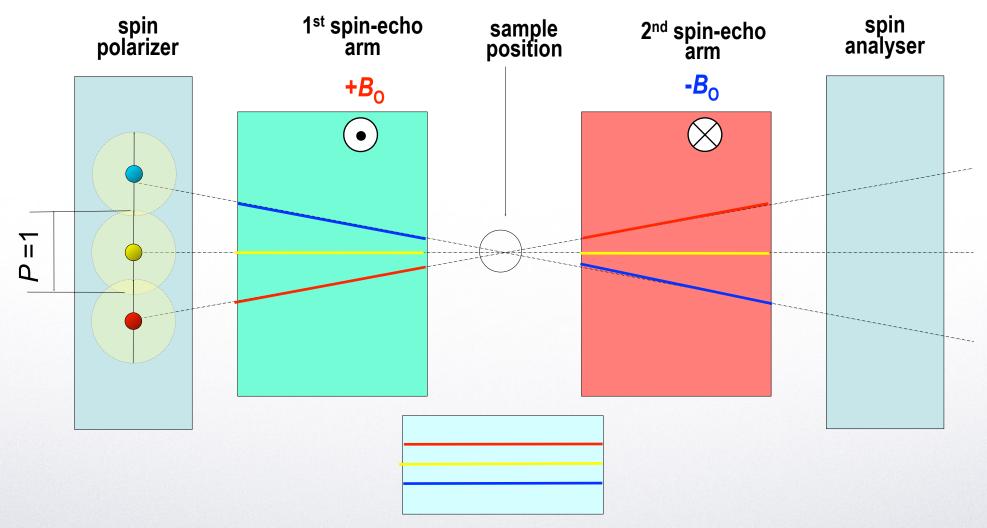


- Neutrons are polarised perpendicular to magnetic fields
- Elastic Case: Neutrons perform the same number of spin rotations in both coils and exit with the original polarisation (spin echo condition)
- Quasielastic Case: Time spent in the second coil will be slightly different, i.e., the original polarisation angle is not recovered (loss in polarisation)

Return

 No strong monochromatisation needed

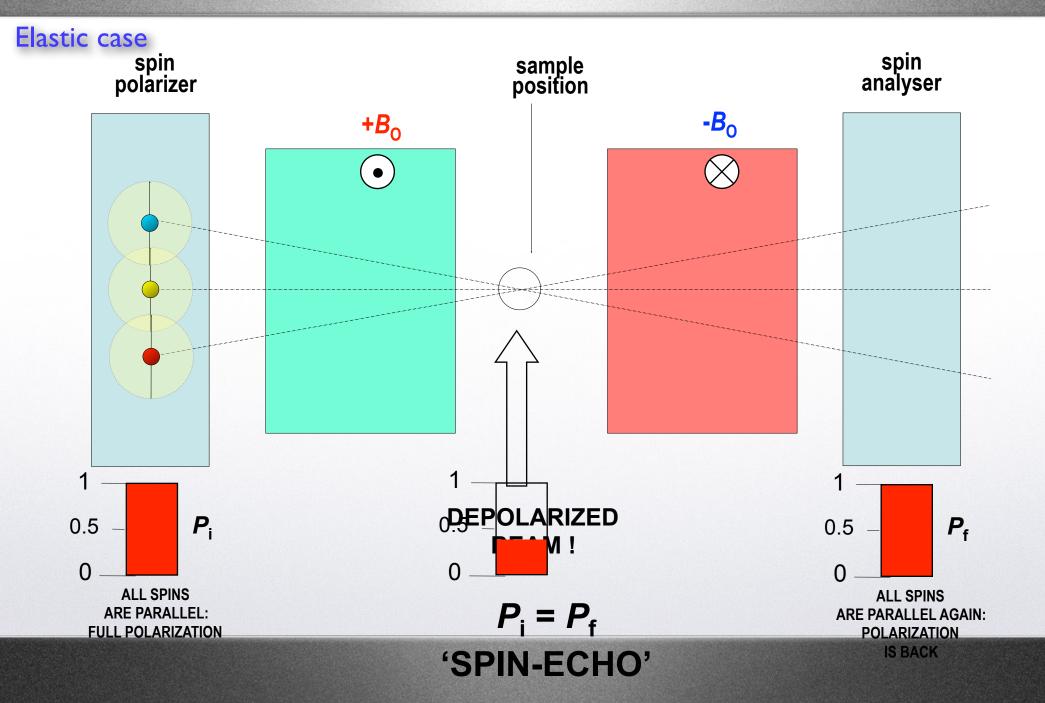
## Fundamentals of NSE



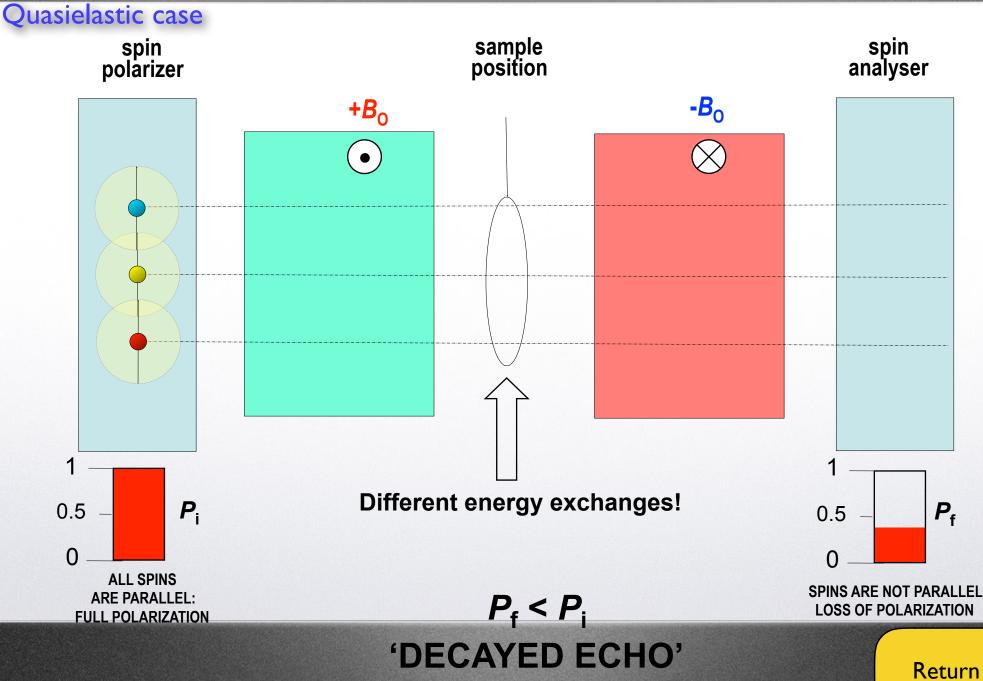
No collimation no monochromatization necessary The echo condition is fulfilled for all paths

Courtesy: Orsolya Czakkel

# ▲ How a NSE spectrometer is built up? < </p>



# ▲ How a NSE spectrometer is built up?



The description of NSE in a classical framework helps to understand the spectrometer operation and its limits.

We start with the classical equation of motion for the Larmor precession of the neutron spin:

$$\frac{d\vec{S}}{dt} = \gamma_L[\vec{S} \times \vec{B}]$$

with the neutron gyromagnetic ratio  $\gamma_{L}$ :

$$\gamma_L = 1.832 \times 10^8 \text{ rad s}^{-1} \text{T}^{-1}$$

The field B from a magnetic coil of length l will create a precession angle  $\boldsymbol{\phi}$ 

$$\varphi = \gamma_L \frac{\int \vec{B} \cdot \vec{dl}}{v}$$
 "Field Integral"  
speed of neutrons  $\Rightarrow$  time spent in the B field

Now we will consider how to link the precession to the dynamics in the sample.

Performing a spin echo experiment we measure the polarisation P with respect to an arbitrarily chosen coordinate x.  $P_x$  is the projection on this axis and we have to take the average over all precession angles:

$$P_x = \langle \cos \varphi \rangle = \langle \cos(\varphi_{in} - \varphi_{out}) \rangle$$

The precession angles  $\varphi_{in}$  and  $\varphi_{out}$  for the neutrons before and after scattering from the sample are given by the respective speeds of the neutrons:

$$P_x = \langle \cos[\gamma_L(\frac{\int \vec{B}_{in} \cdot \vec{dl}}{v_{in}} - \frac{\int \vec{B}_{out} \cdot \vec{dl}}{v_{out}})] \rangle$$

To first order  $\varphi$  is proportional to the energy transfer at the sample  $\omega$  with the proportionality constant *t* (spin echo time).

$$\varphi = t\omega$$

This is the "fundamental equation" of classical neutron spin echo.

We consider the "fundamental equation"  $\varphi = t\omega$  and we will calculate t to first order by Taylor expansion.

Starting point is the energy transfer  $\omega$ :

$$\hbar\omega = \frac{m}{2} \left[ (\bar{v} + \Delta v_{out})^2 - (\bar{v} + \Delta v_{in})^2 \right]$$

Taylor expansion to first order gives:

$$\omega = \frac{m}{\hbar} \left[ \bar{v} \Delta v_{out} - \bar{v} \Delta v_{in} \right]$$

Now we turn to the phase  $\varphi$ :

$$\varphi = \gamma_L \left[ \frac{\int \vec{B} \cdot \vec{dl}}{\bar{v} + \Delta v_{in}} - \frac{\int \vec{B} \cdot \vec{dl}}{\bar{v} + \Delta v_{out}} \right]$$

Here, Taylor expansion to first order gives:

$$\varphi = \gamma_L \left[ \frac{\int \vec{B} \cdot d\vec{l}}{\bar{v}^2} \Delta v_{out} - \frac{\int \vec{B} \cdot d\vec{l}}{\bar{v}^2} \Delta v_{in} \right]$$

Combining the equations for  $\omega$  and  $\varphi$ , we get:  $t = \frac{\varphi}{\omega} = \frac{\hbar}{m} \frac{\gamma_L \int \vec{B} \cdot \vec{dl}}{\vec{v}^3} = \frac{m^2 \gamma_L \int \vec{B} \cdot \vec{dl}}{2\pi h^2} \lambda^3$ 

using de Broglie  $p = mv = \frac{h}{\lambda}$ 

We consider the "fundamental equation"  $\varphi = t\omega$  and we will calculate t to first order by Taylor expansion.

Starting point is the energy transfer  $\omega$ :

$$\hbar\omega = \frac{m}{2} \left[ (\bar{v} + \Delta v_{out})^2 - (\bar{v} + \Delta v_{in})^2 \right]$$

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Here, Taylor expansion to first order gives:

$$\varphi = \gamma_L \left[ \frac{\int \vec{B} \cdot d\vec{l}}{\bar{v}^2} \Delta v_{out} - \frac{\int \vec{B} \cdot d\vec{l}}{\bar{v}^2} \Delta v_{in} \right]$$

Combining the equations for  $\omega$  and  $\varphi$ , we get:  $t = \frac{\varphi}{\omega} = \frac{\hbar}{m} \frac{\gamma_L \int \vec{B} \cdot \vec{dl}}{\bar{v}^3} = \frac{m^2 \gamma_L \int \vec{B} \cdot \vec{dl}}{2\pi h^2} \quad \text{using de Broglie} \quad p = mv = \frac{h}{\lambda}$ 

We return to the equation for the **polarization**  $P_x$ 

$$P_x = \langle \cos \varphi \rangle = \langle \cos(\omega t) \rangle$$

and use it to prove that we measure the intermediate scattering function. In a first step we write down the average as an integral

$$P_x(Q,t) = \frac{\int S(Q,\omega) \cos(\omega t) d\omega}{\int S(Q,\omega) d\omega}$$

Here, we exploit that the scattering function  $S(Q, \omega)$  is the probability for scattering a neutron with a given momentum and energy transfer.

It turns out that  $P_x$  is the cosine transform of the  $S(Q, \omega)$ . Thus,  $P_x$  is not strictly equal to the intermediate scattering function, but to the real part only.

$$P_x(Q,t) = \frac{\Re(I(Q,t))}{I(Q,0)}$$

For most cases this different is negligible, but this has to be kept in mind.

### The measurement principle of neutron spin echo spectroscopy Example:

We consider a quasielastic Lorentzian line:

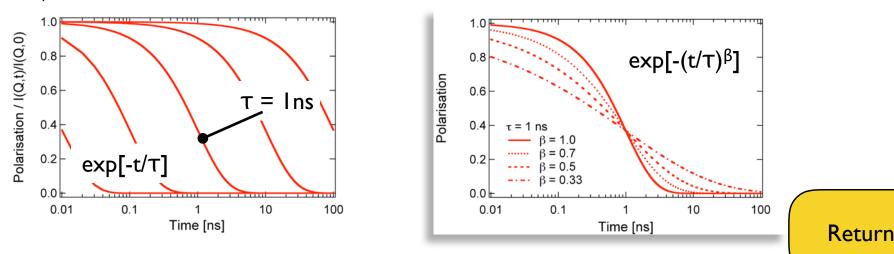
$$S(Q,\omega) \propto rac{\Gamma}{\Gamma^2 + \omega^2}$$

For a Lorentzian line, the Fourier transform is an exponential decay function:

$$P_x(Q,t) = \frac{\int [\Gamma^2 + \omega^2]^{-1} \cos(\omega t) d\omega}{\int [\Gamma^2 + \omega^2]^{-1} d\omega} = e^{-\Gamma t} = e^{-t/\tau}$$

 $\Gamma$  is the quasi-elastic line broadening and  $\tau$  is the decay/relaxation time.

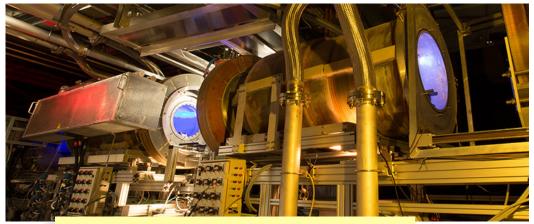
For a mixture of relaxation times we often get a good description by a **stretched exponential** function  $\exp[-(t/\tau)^{\beta}]$  (this is also called KWW Kohlrausch Williams Watt function).



## Spin Echo Spectrometers at ILL



Mezei's first spin echo precession coils



Today's IN15: measures up to 1 µs

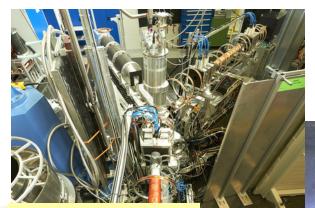


Large angle NSE: INTIC for high signal



Spin-echo option TASSE @ TAS spectrometer IN20

## Spin echo spectrometers in Europe

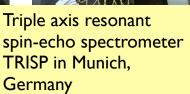


Resonant NSE RESEDA in Munich, Germany



High resolution spectrometer J-NSE in Munich, Germany

RNSE option on TAS spectrometer FLEXX in Berlin, Germany







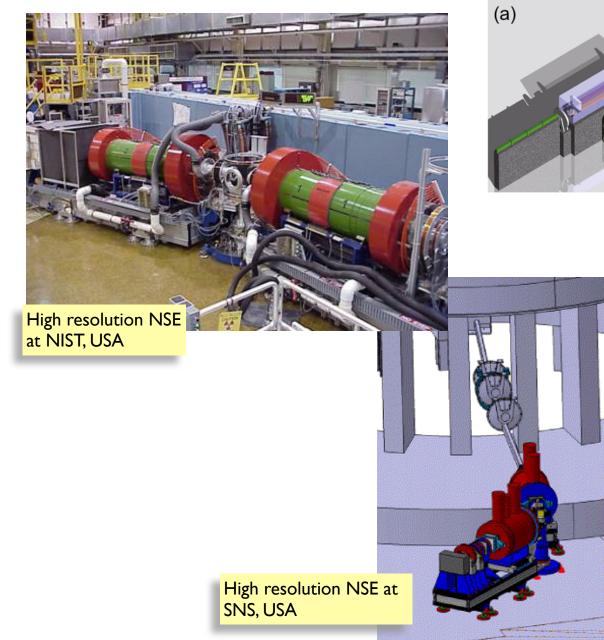
Spin-echo SANS with optional NSE OFFSEC at ISIS, UK

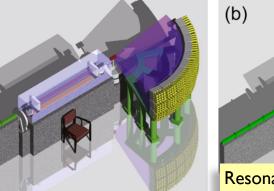


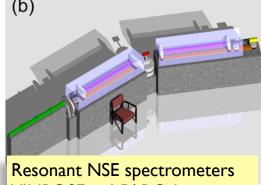
at ISIS, UK

Multi-purpose spin precession instrument LARMOR at ISIS, UK

## Spin echo spectrometers in the World

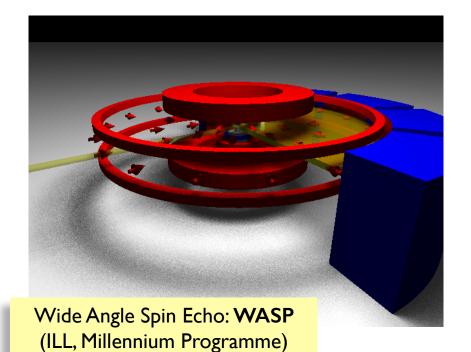






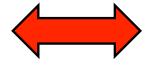
VINROSE at J-PARC, Japan

Spin echo spectrometers around the world: Major trends in instrument development



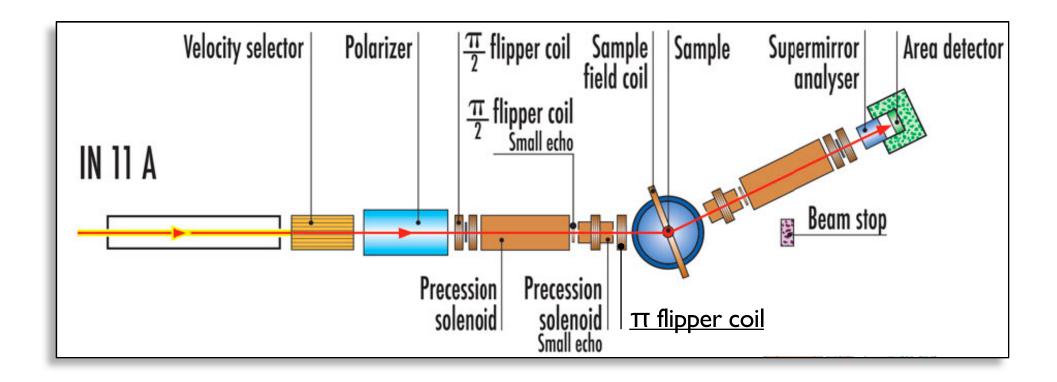
Highest resolution spectrometer IN15 (ILL millennium update)

Large Signal/ High Q



High Resolution/ Small Q





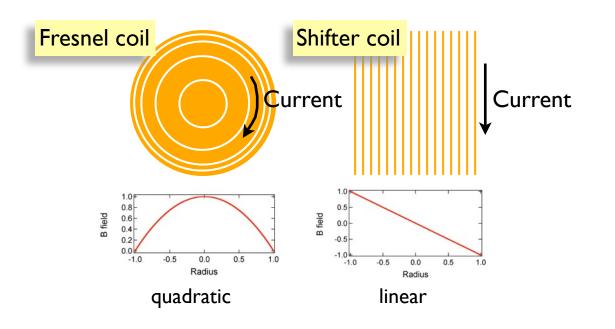
- The beam is monochromatised by a velocity selector to about dv/v = 15 %
- Spin polarization and analysis are performed by supermirrors
- Spin precession is started and stopped by  $\pi/2$  (or 90°) spin flipper coils
- The fields  $B_{in}$  and  $B_{out}$  are parallel and, therefore, a 180° or  $\pi$  flipper coil is necessary
- Small times are reached by "Small Echo" coils

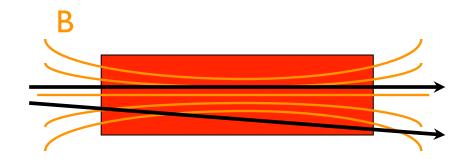
## How a spin echo spectrometer works: Correction elements

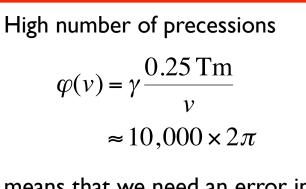
We consider again the precession angle:

$$\varphi(v) = \gamma \frac{\int \mathbf{B} \cdot \mathbf{dl}}{v}$$

This angle should be the same for all neutrons with the same velocity - irrespective of their trajectories!







means that we need an error in the field integral of about:

$$\frac{\Delta \int \mathbf{B} \cdot \mathbf{dl}}{\int \mathbf{B} \cdot \mathbf{dl}} \le 10^{-6}$$

### Discrimination methods for coherent, incoherent and magnetic dynamics

Up to now, we have neglected spin interactions with the sample, but they are important!

We include this effect by introducing a *pre-factor*  $P_s$  to the calculation of  $P_x$ :

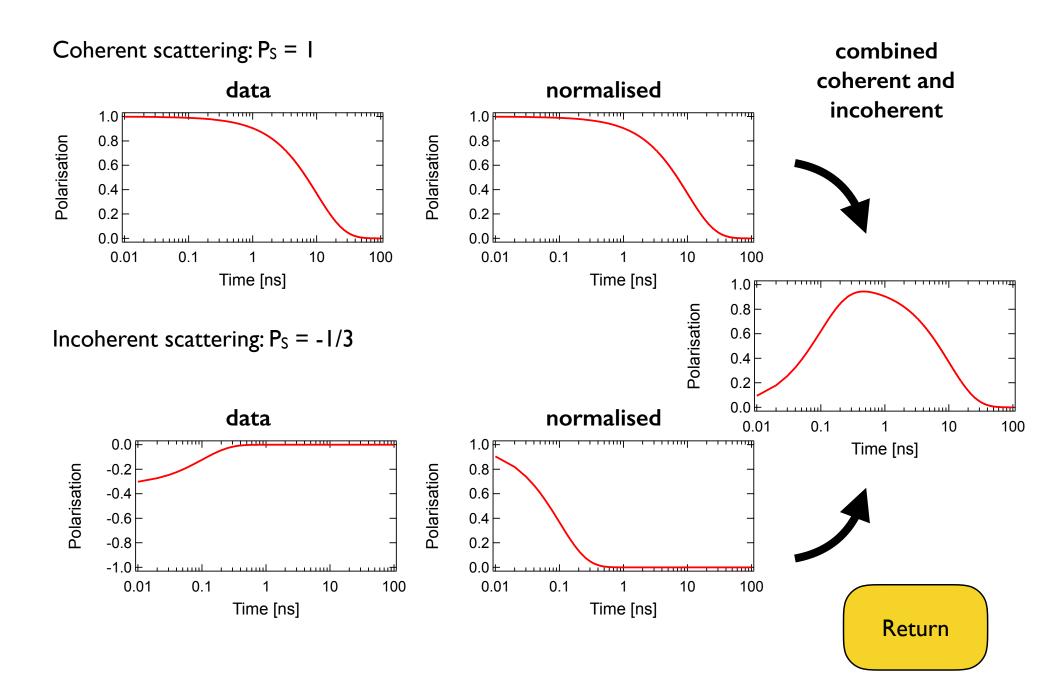
$$P_x(Q,t) = P_s \frac{\Re(I(Q,t))}{I(Q,0)}$$

In addition, spin interactions with the sample can lead to an apparent  $\pi$  flip by the sample  $\Rightarrow$  for paramagnetic samples a  $\pi$  flipper coil is not used.

The ratio of coherent/incoherent signal can be critical.

Type of scatterer	Spin flip coils needed	Sample field	Ps	
Coherent and isotope-incoherent	$\pi$ flipper	small	I	_
Spin-incoherent	$\pi$ flipper	small	-1/3	
Paramagnet	none	small	1/2	
Ferromagnet	$2 \pi/2$ flippers	high	1/2	
Antiferromagnet	none	small	1/2-1	Return

### What happens if coherent and incoherent scattering co-exist



#### 1.0 F incoherent 0.8 fraction Partial coherent/incoherent signal 0.6 coherent scattering 0.4 1.0 incoherent scattering Polarisation 0.8 coherent fraction 0.6 0.0 0.2 8 0.4 -0.2 Polarisation 00 0.2 -0.4 0.0 0.0 -0.6 0.01 10 0.1 100 Ο Q -0.8 Time [ns] -1.0 -0.2 0.01 10 100 0.1 1 polarisation Time [ns] -0.4 0.0 0.2 0.4 0.6 0.8 1.0 1.2 mixed signal Q [1/Å] 1.0 Polarisation 0.8 0.6 0.4 0.2 0.0 0.01 0.1 10 100 Return 1 Time [ns]

### What happens if coherent and incoherent scattering co-exist

#### 1.0日 incoherent 0.8 fraction erent signal 0.6 coherent scattering 1.0 incoherent scattering Polarisation 0.8 coherent fraction Partial coherent/in 0.6 0.2 0.0 0.4 ation -0.2 0.2 0.0 0.0 <del>300</del>, -0.6 Pola 0.01 10 0.1 100 -0.8 Time [ns] -1.0 -0.2 0.01 10 100 0.1 1 polarisation Time [ns] 0.0 0.2 0.4 0.6 0.8 1.0 1.2 mixed signal Q [1/Å] 1.0 Polarisation 0.8 0.6 0.4 0.2 0.0 0.01 0.1 10 100 Return 1 Time [ns]

### What happens if coherent and incoherent scattering co-exist

## Measuring an NSE Spectrum and the "4-point method"

### • An NSE spectrum is measured stepwise and not "continually"

- A spin echo time is set by sending the same current *I*∝*B* through both coils
- For each spin echo time, the signal is measured as the phase  $\phi$  is scanned by applying a small offset current
- In the "4-point method" we measure the projection of the polarization as we change φ in steps of 90 around the spin-echo point

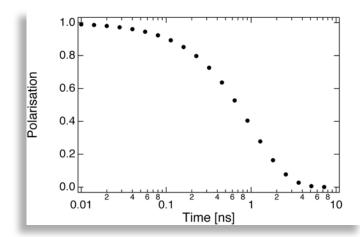
This gives us:

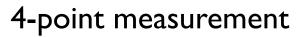
• average signal A, amplitude I, phase shift  $\Delta \phi$ and frequency f

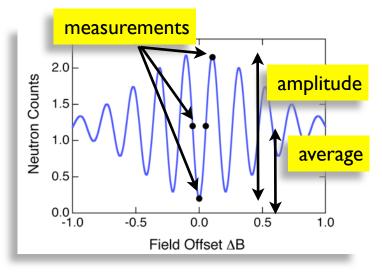
From these measurements we can extract:

• the polarization P = I/A

## **Typical NSE Spectrum**







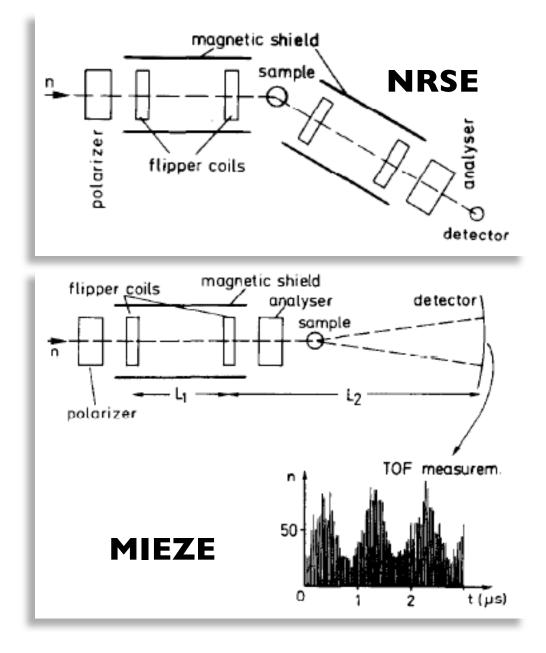
## Neutron **Resonance** Spin Echo (NRSE)

The principle of neutron resonance spin echo:

 Instead of rotation of neutron spins, NRSE uses rotation of fields

Technical realisation:

- NRSE uses spin flipper coils with rotating field directions
- Between flipper coils the B field is 0
- Flipper coils can be inclined for inelastic line width measurements
- Ideal for combination with TAS
- NRSE can be extended to MIEZE technique (second arm flippers replaced by ToF detection scheme)



R. Gähler et al., Physica B 180-181 (1992) 899

#### Return

## Spin Echo Small Angle Neutron Scattering (SESANS)

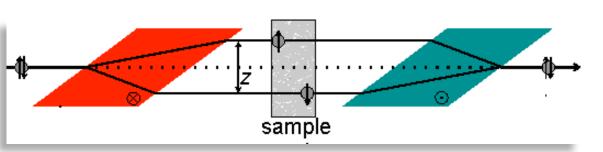
The aim of SESANS:

• Studying structure on very large scale

The basic principle:

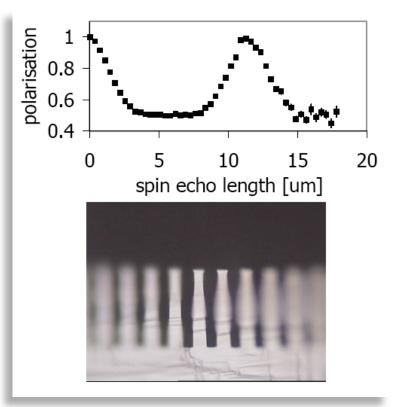
- Splitting neutron wave function *spatially* into two partial wave functions
- This is achieved by coils with inclined faces

## SESANS Set-Up



W. Bouwman et al., TU Delft

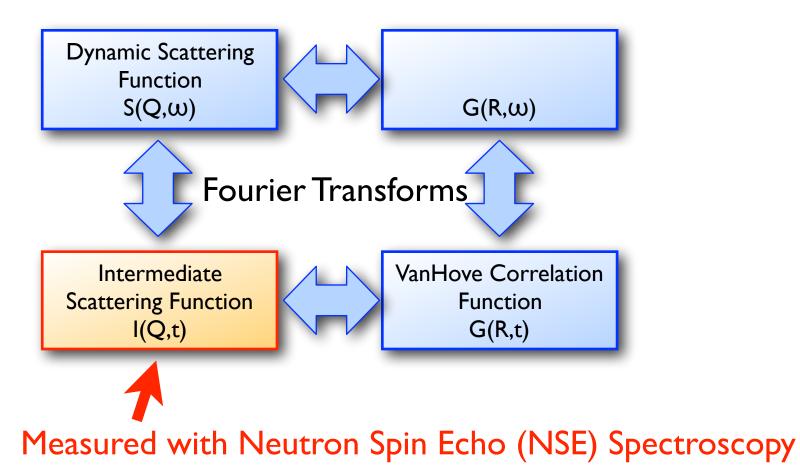
SESANS Example: Silicon Grating



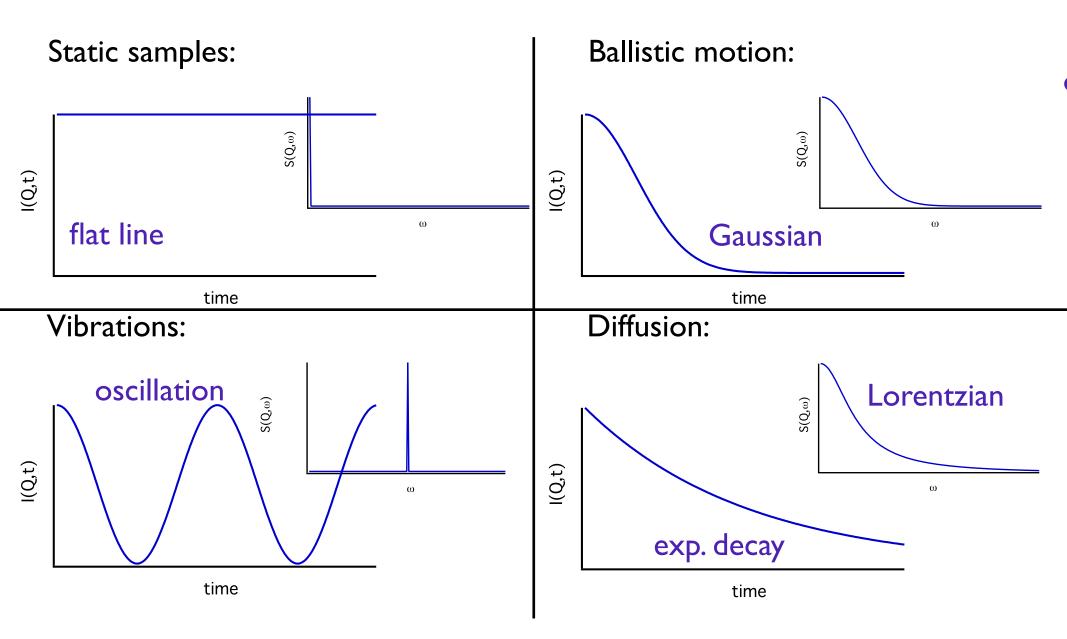
M.Trinker et al. NIMA 579 (2007) 1081

## How to do Science using NSE

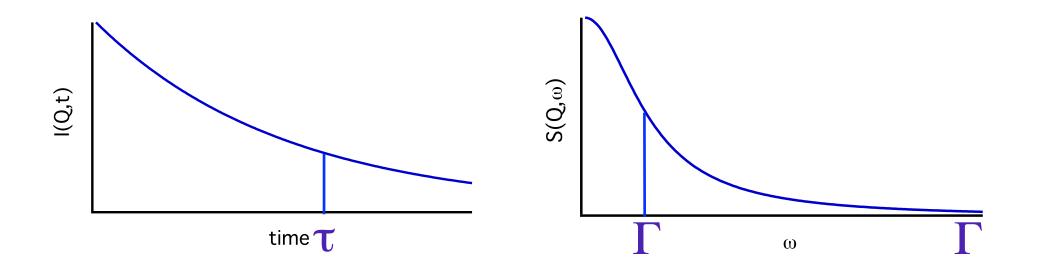
NSE measures I(Q,t), the intermediate scattering function



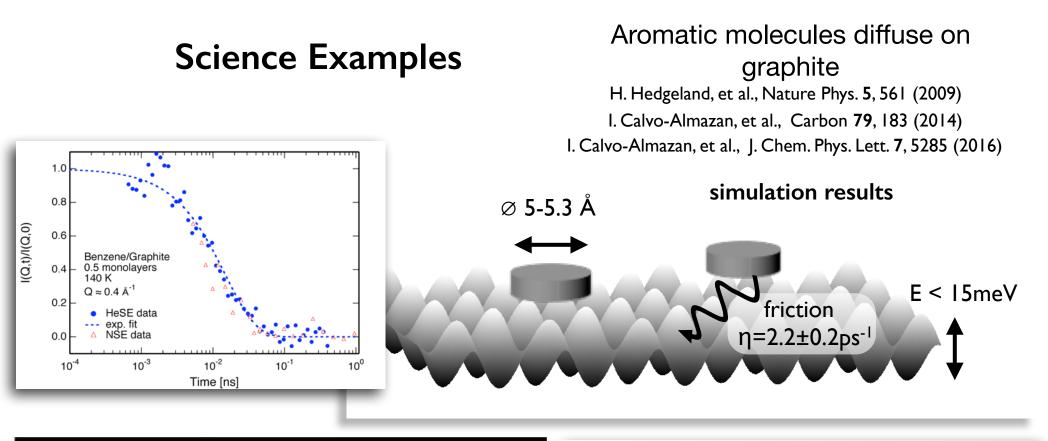
The shape of the decay curve tells us already a story

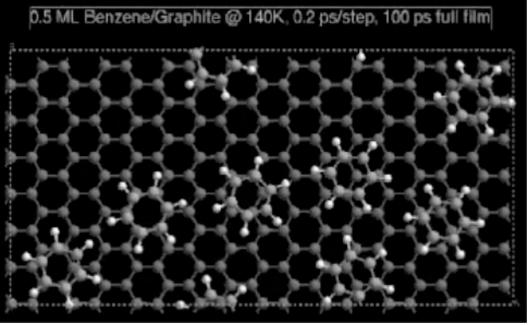


The shape of the decay curve tells us already a story



 $\tau = h/\Gamma$ 



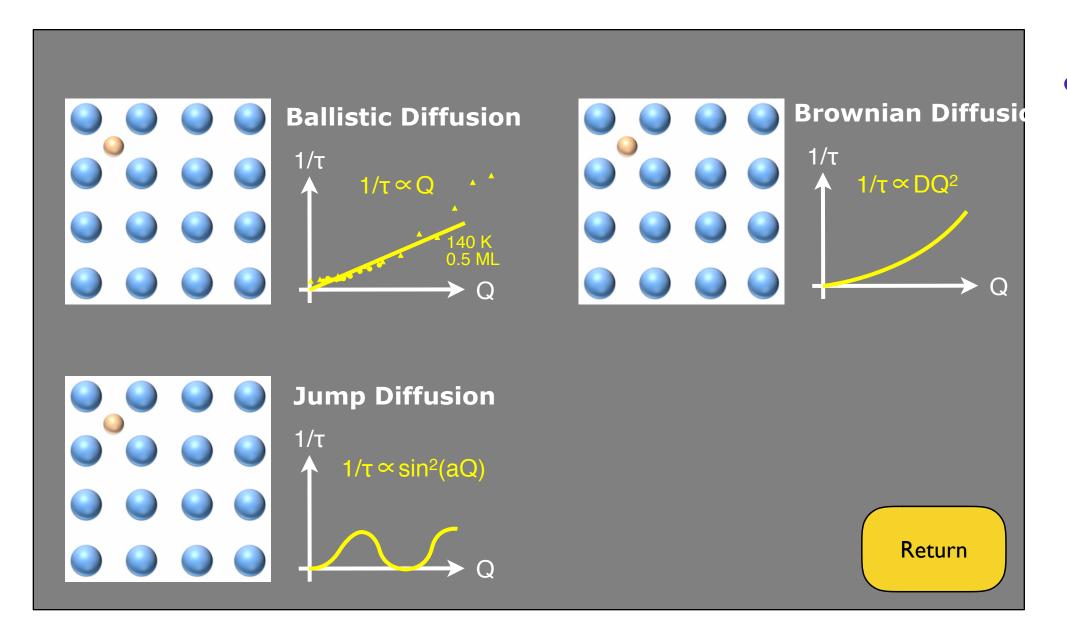


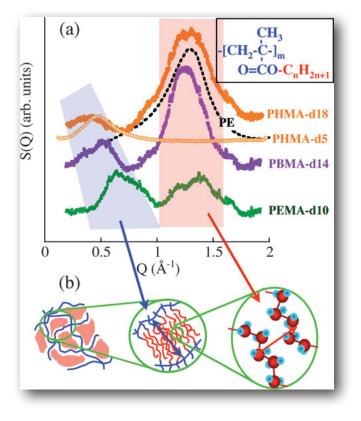
NSE - and its surface equivalent helium spin-echo - see "perfect" molecular Brownian diffusion.

Data can be reproduced with molecular dynamics (MD) simulations.

Dynamic friction can be determined.

## We can exploit the Q dependence of tau or Gamma



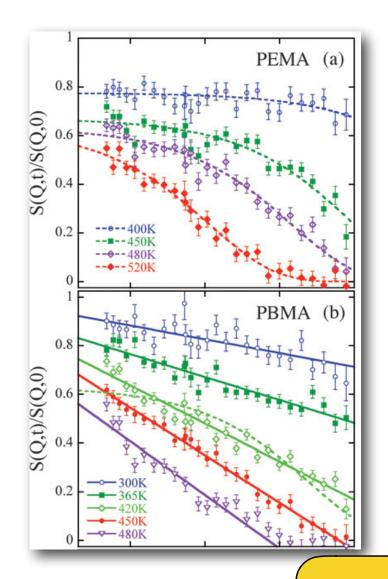


In different Q regions, dynamics can be profoundly different:

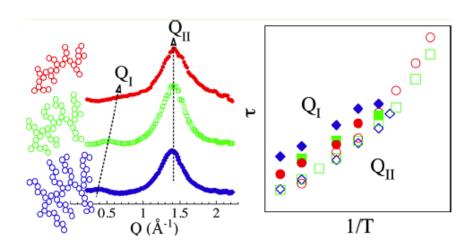
PnMA polymers, show standard KWW decay on the low Q range and logarithmic decay in the region of the nano domains

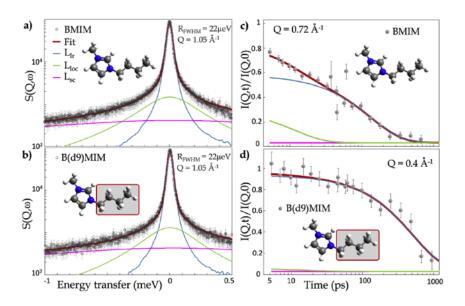
## **Science Examples**

**Dynamics of Polymers - Length Scales** 



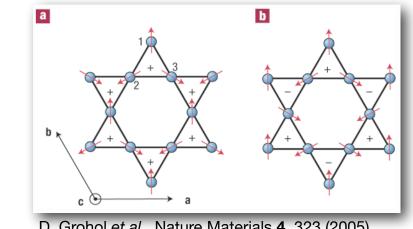
Dynamic differences of asymmetric comb-like polymers disappear at high T A. Arbe et al., Macromolecules **49**, 4989 (2016) Evidence for the scaledependence of the viscosity of ionic liquids Q. Berrod et al., Scientific Reports **7**, 2241 (2017)



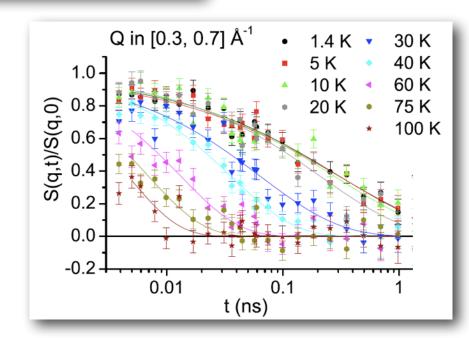


### Dynamics of Frustrated Magnets: Nd langasite

V. Simonet et al., Phys. Rev. Lett. 100, 237204 (2008)







τ (ns)

0.1

0.01

0.01

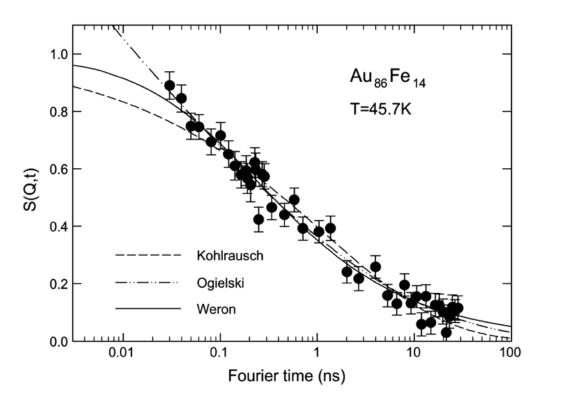
0.1

1/T(K)

NSE is strong in magnetism research as it can distinguish between magnetic and non-magnetic dynamics.

Nd<sub>3</sub>Ga<sub>5</sub>SiO<sub>14</sub> is a **frustrated magnet** with a 2 dim. "Kagome" lattice. Such systems have no fixed spin orientation and are highly dynamic.

Here, a **quantum relaxation** hides the effects of frustration.

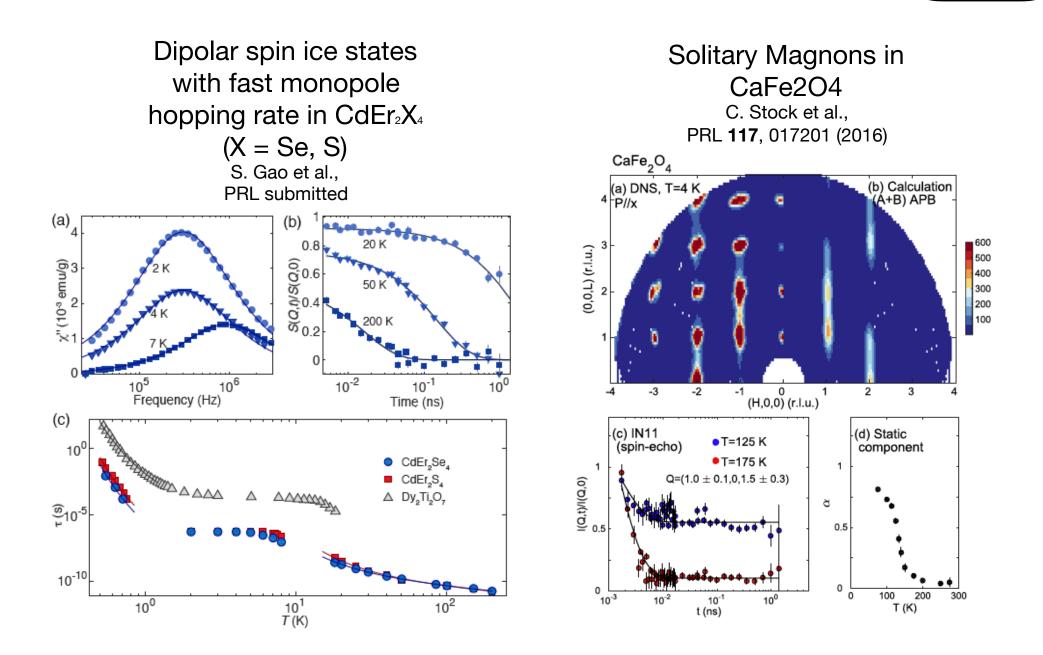


Determination of line shape of relaxation

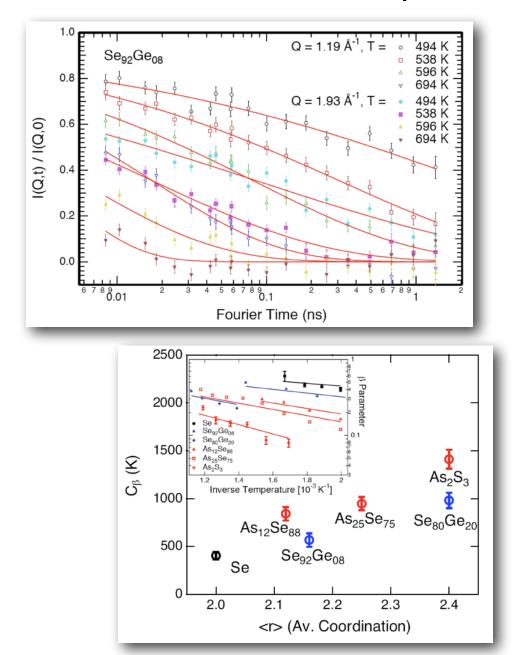
Limited by **statistics** and **spectroscopic range** 

Return

Cywinski, Pappas et al. PRL **102**, 097202 (2009)



### Dynamics of **Glasses**



 $Ge_xAs_ySe_{1-x-y}$  alloy is a network glass

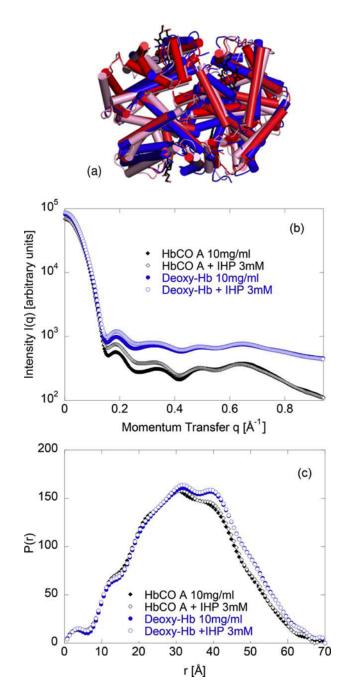
Normal liquid dynamics show a thermal activation according to  $exp[-kT/E_a]$ 

Dynamics of glasses close to the transition temperature, however, show sometimes strong deviations from exponential behaviour

With measurements on INTT it was possible to see this effect even far away from the glass transition and the dynamics were linked to the **average co-ordination number <r>**:

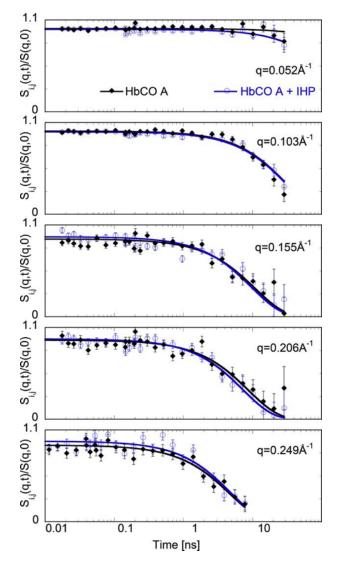
$$= 4x + 3y + 2(1-x-y)$$

J. Bermejo et al., Phys. Rev. Lett. 100, 245902 (2008)



## Dynamics of Biomolecules: Hemoglobin

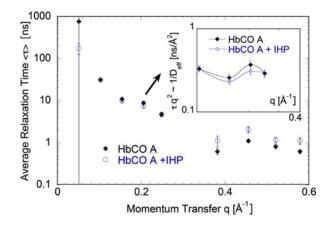
J. Lal et al. Protein Science 26, 505-514 (2017)



Change of hemoglobin dynamics by an allosteric affector molecule

Hemoglobin structure is different when IHP is attached (true for empty and CO-filled)

Small dynamic changes are observed by NSE



## **Strengths and Weaknesses of Neutron Spin Echo**

## **Strong Points**

- I. Highest energy resolution of all neutron scattering techniques
- 2. Large dynamic range
- 3. Relaxation is measured directly as function of time
- 4. Coherent, Incoherent and magnetic scattering can be discriminated
- 5. Sample signal high due to weak monochromatisation of incoming neutrons

### Weak Points

- I. Signal is often weak, because detector solid angles are, generally, small
- 2. Q resolution is, generally, not very high if velocity selector is used
- 3. Standard NSE spectrometers are sensitive to magnetic field environment
- 4. Incoherent scattering can lead to very bad signal-to-noise ratio

## Literature

Ferenc Mezei (Ed.):

Neutron Spin-Echo, Lecture Notes in Physics 128, Springer, Heidelberg, 1980.

Stephen Lovesey:

Theory of Neutron Scattering from Condensed Matter, Vol. 2, Clarendon Press, Oxford, 1986.

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