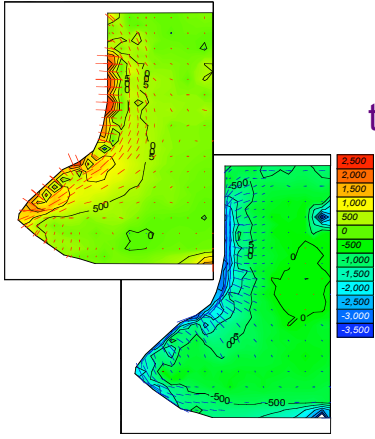


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Engineering
Advanced diffraction
techniques for Residual Stress
determination

Michael Preuss
University of Manchester

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Introduction

- Residual stresses in materials
- Principles of measuring residual stresses by diffraction
- Neutron and Synchrotron X-ray diffraction
 - Properties
 - Facilities
- Case Studies / Questions
- From Engineering to Physical Metallurgy – Understanding plasticity
- Conclusions

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What are residual stresses

Deformation mismatch

Example: Welding

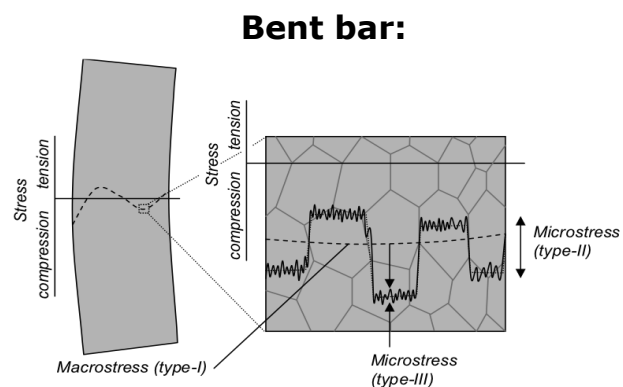


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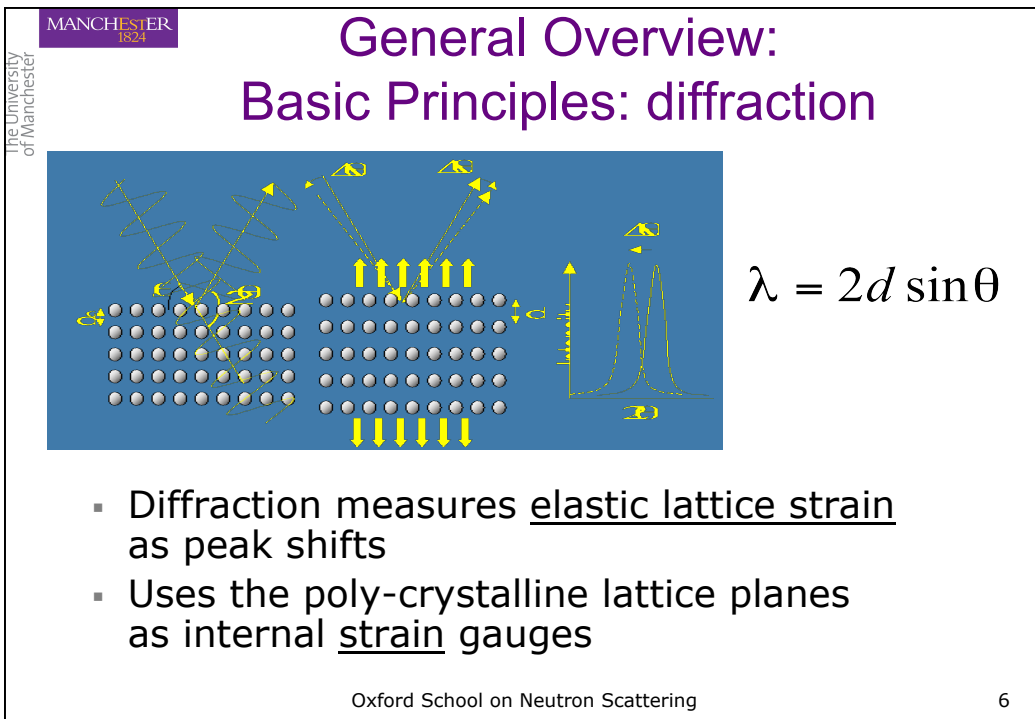
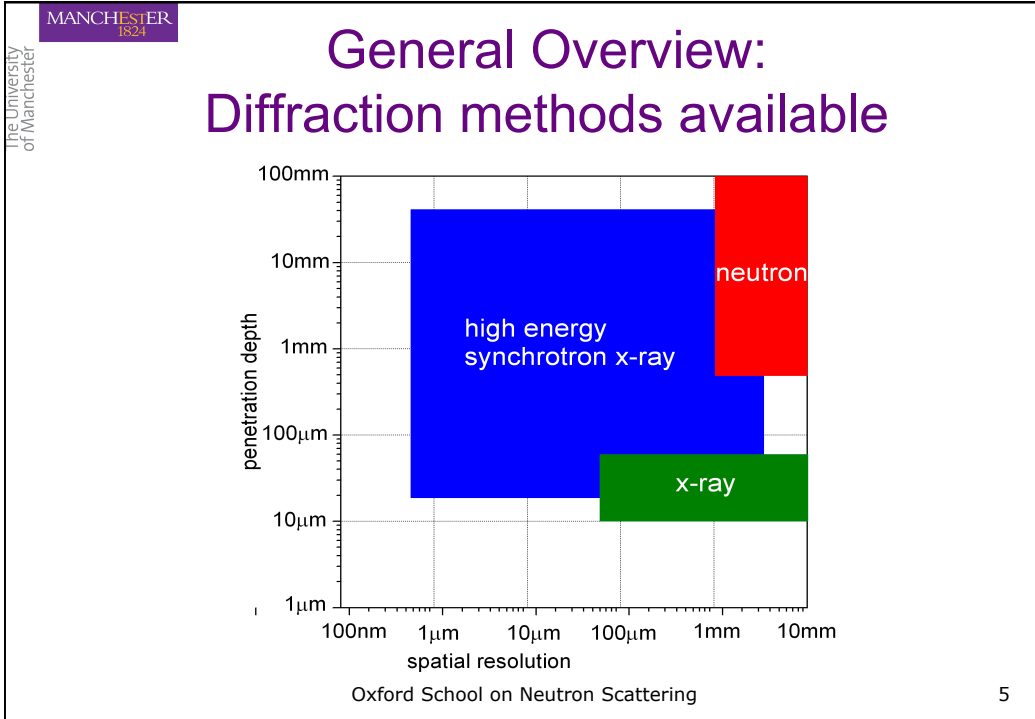
Residual Stresses

- Internal stresses
- Caused by misfit
 - Type I
 - Type II
 - Type III

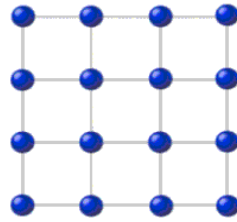


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Basic Principle



Bragg scattering angle

wavelength:

$$\lambda = \frac{hc}{E} = \frac{12.39}{[keV]}$$

Bragg's law:

$$\lambda = 2d \sin \theta$$

Scattering Angle

$$\theta = \arcsin \left(\frac{12.39}{2d[keV]} \right)^{\frac{1}{2}}$$

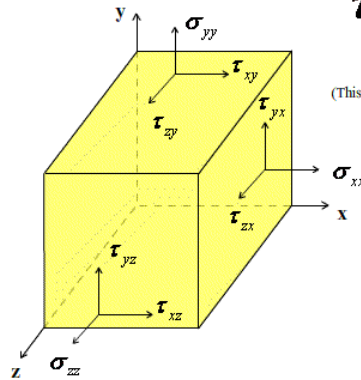
$$\frac{12.39}{[keV]} = 2d \sin \theta$$

General Overview: Basic Principles

- Measured strains have to be converted into stresses! (Hooke's law)

$$\varepsilon = \frac{a - a_0}{a_0} = \frac{d - d_0}{d_0}$$

The 9 components of a stress tensor:



The stress acts in the x-direction
 τ_{xy}
 on the plane with a normal in the y direction
 (This convention maybe vice versa in some books.)

$$\sigma_{ij} = \begin{pmatrix} \sigma_{xx} & \tau_{xy} & \tau_{xz} \\ \tau_{yx} & \sigma_{yy} & \tau_{yz} \\ \tau_{zx} & \tau_{zy} & \sigma_{zz} \end{pmatrix}$$

Tensor Equation: $\sigma_{ij} = C_{ijkl} \varepsilon_{kl}$

Matrix Equation: $\sigma_p = C_{pq} \varepsilon_q$

General Overview: Basic Principles

- Measured strains have to be converted into stresses! (Hooke's law)

$$\varepsilon = \frac{a - a_0}{a_0} = \frac{d - d_0}{d_0}$$

e.g. isotropic triaxial
 along principal
 directions:

$$\varepsilon_{11} = \frac{1}{E} [\sigma_{11} - \nu(\sigma_{22} + \sigma_{33})]$$

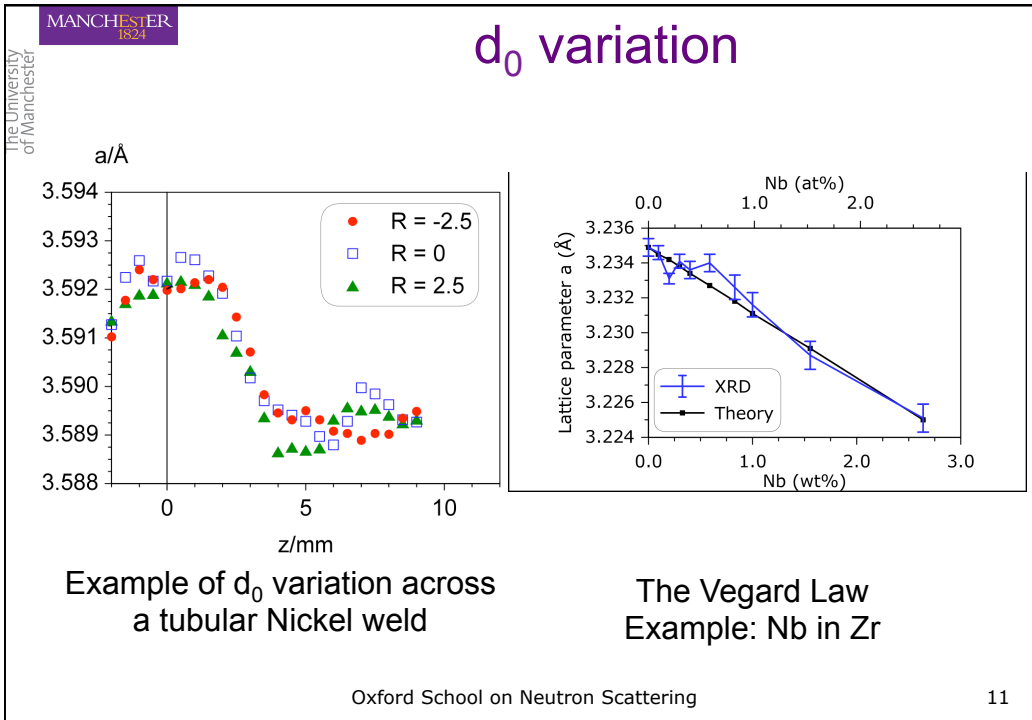
$$\varepsilon_{22} = \frac{1}{E} [\sigma_{22} - \nu(\sigma_{33} + \sigma_{11})]$$

$$\varepsilon_{33} = \frac{1}{E} [\sigma_{33} - \nu(\sigma_{11} + \sigma_{22})]$$

To calculate a stress direction:

$$\sigma_{11} = \frac{E}{(1 + \nu)(1 - 2\nu)} [(1 - \nu)\varepsilon_{11} + \nu(\varepsilon_{22} + \varepsilon_{33})]$$

(Attention: not always this simple!)



Why do we like neutrons ?

- Part of the nucleus
- Same mass as protons
- Interesting wavelength/mass relationship:

$$\lambda = \frac{h}{p} = \frac{h}{mv}$$

← Planck

← Mass * Velocity
- “Thermal” neutrons: wavelength similar to those of X-rays 0.5-5Å similar to atomic spacing in solids
- Allows cubic gauge volumes!
- Relatively divergent beam !!

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Neutron and Synchrotron Sources


Neutron:

- Reactor Sources (Fission)
 - Constant wavelength/Single Peak
- Accelerator Sources (Spallation)
 - Time-of-flight / Full Spectra / Rietveld


Synchrotron:

- Monochromatic λ and white beam

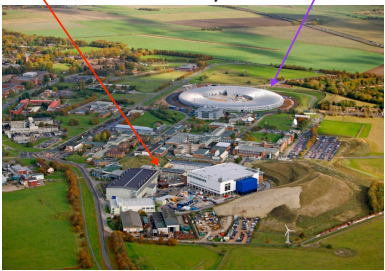
ESRF
Grenoble, France



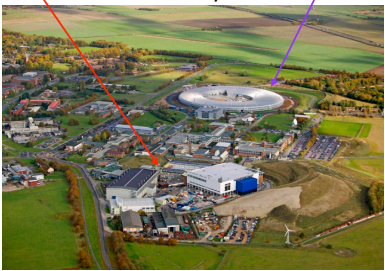
ILL
Grenoble, France



ISIS
Chilton, UK



Diamond
Chilton, UK



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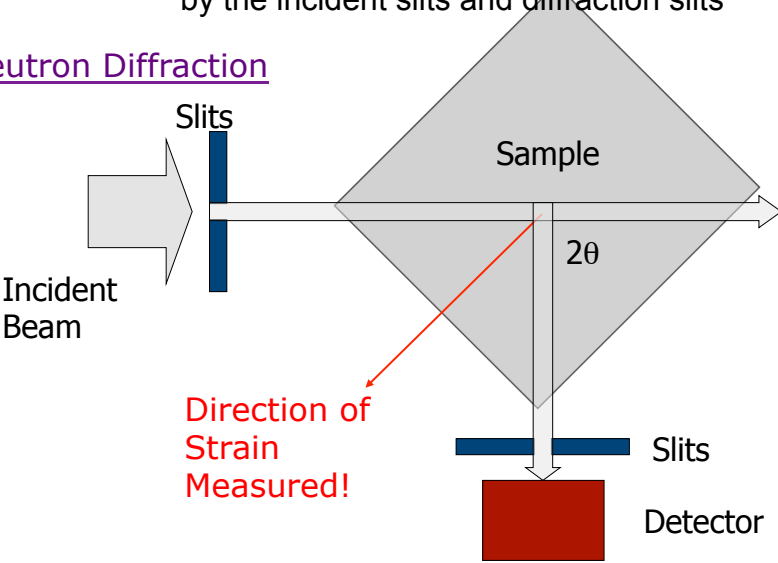
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General Overview: Strain Scanning

Diffracting Gauge Volume: The volume element defined by the incident slits and diffraction slits

Neutron Diffraction



Incident Beam

Slits

Sample

2θ

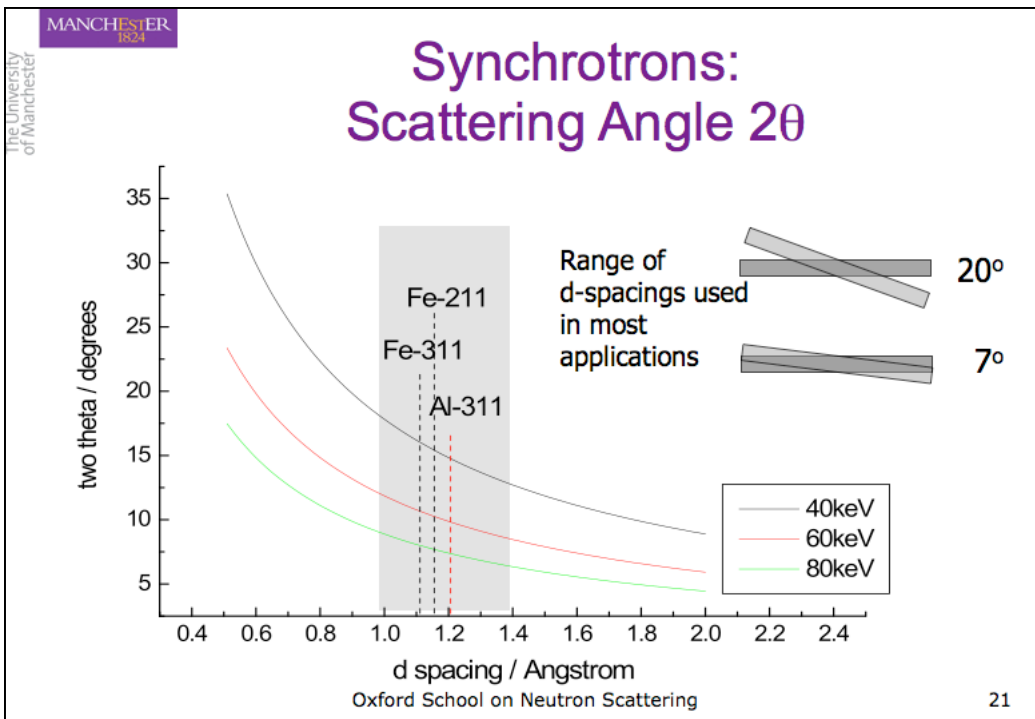
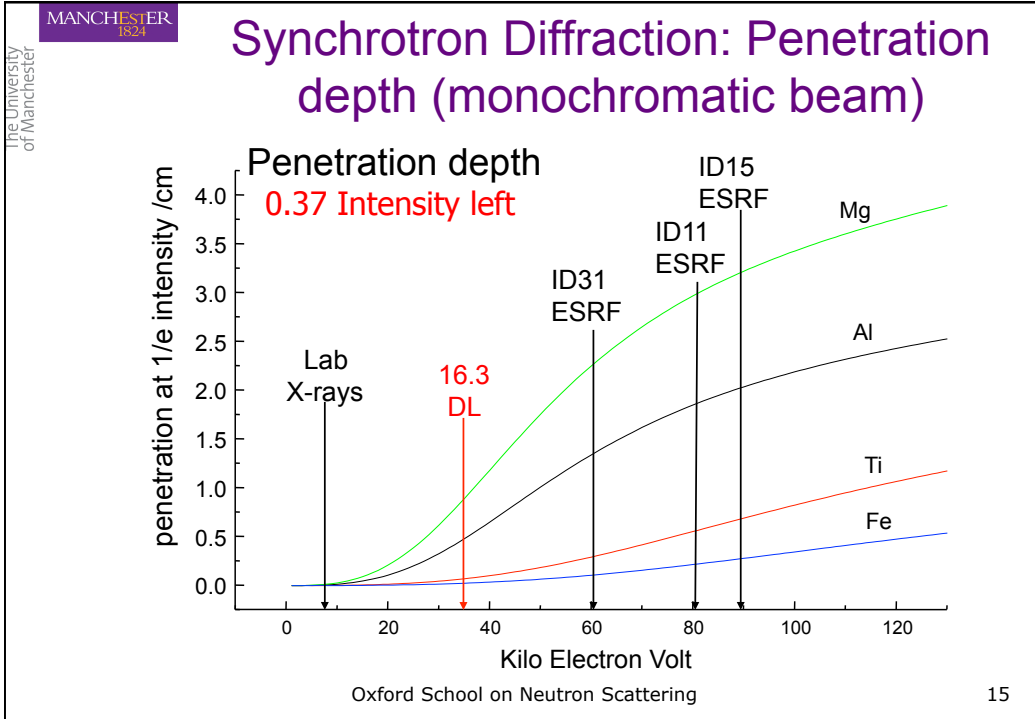
Direction of Strain Measured!

Slits

Detector

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General Overview: Diffracting Gauge Volume

Volume element of the material in which the recorded scattering takes place

- Results in averaged d-spacing (powder diffraction - many grains)
- Defines the minimum spatial resolution of the method (around 1mm^3 minimum gauge volume when using neutron diffraction)
- and type of residual stress resolved (macro-stress or type-I usually. Type-II for two phase materials).
- Use the largest possible gauge volume for your specific issue in order to minimise counting time

Near surface measurements

Neither peak shift (strain) nor measurement location is correct near a surface!

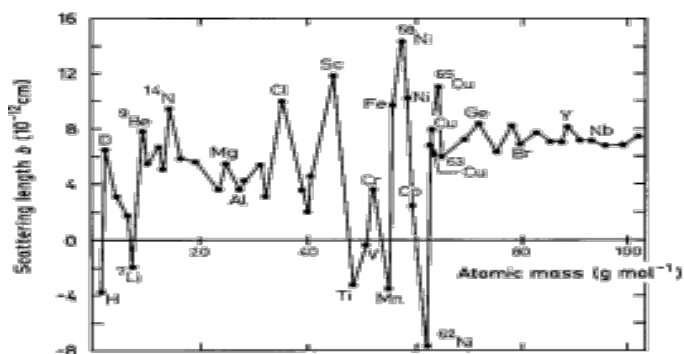
- Partial filling of sampling gauge gives a peak shift - **need to correct peak shift**
- Translator records centre of gauge which is rarely the centre of gravity of diffracting region
- **need to correct gauge position**

Neutron Properties

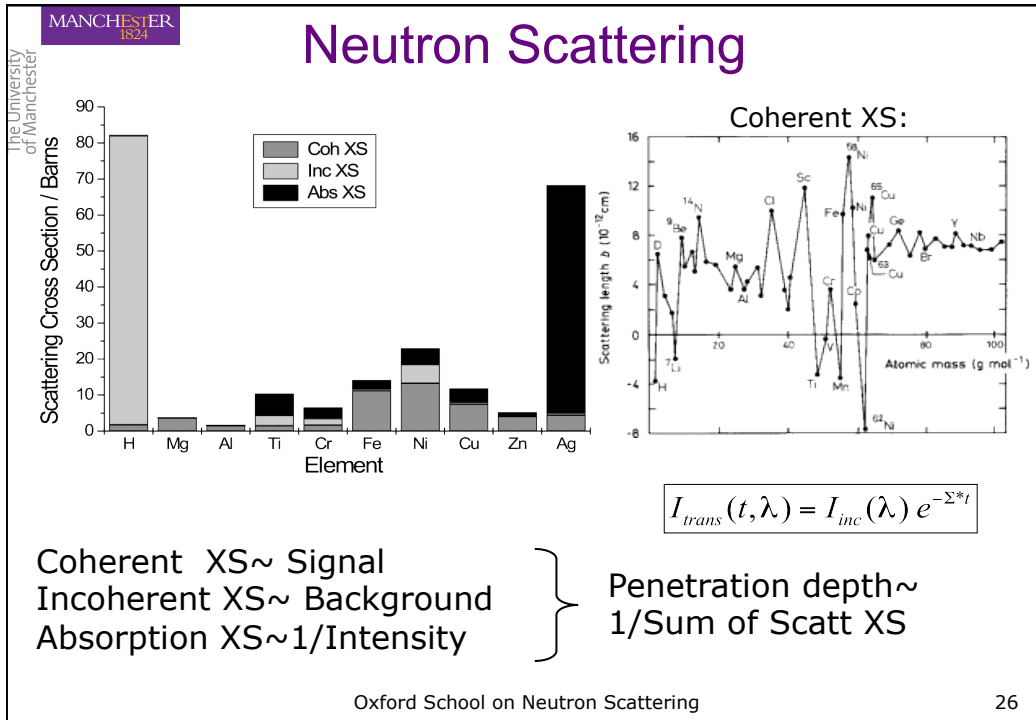
- Neutrons are scattered by atomic nuclei (electrons and X-rays which are scattered by the electron cloud).
- Since the scattering is nuclear process, scattering amplitude varies greatly for different isotopes of same element and in a unpredictable manner from element to element. X-ray and electron scattering increase monotonically with atomic number

Neutron Properties

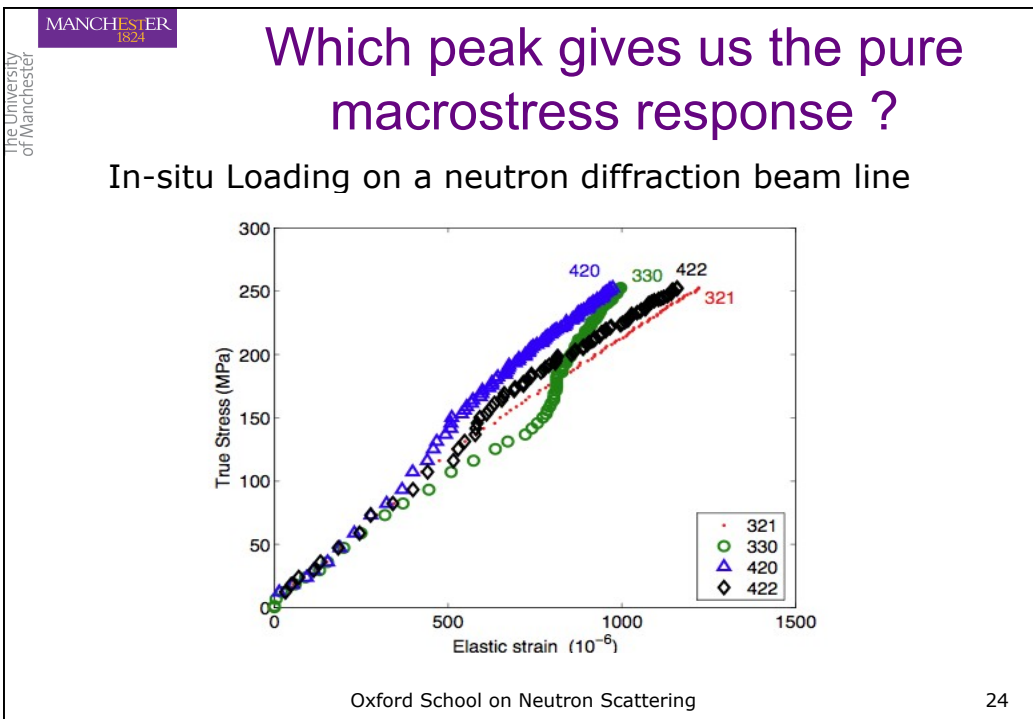
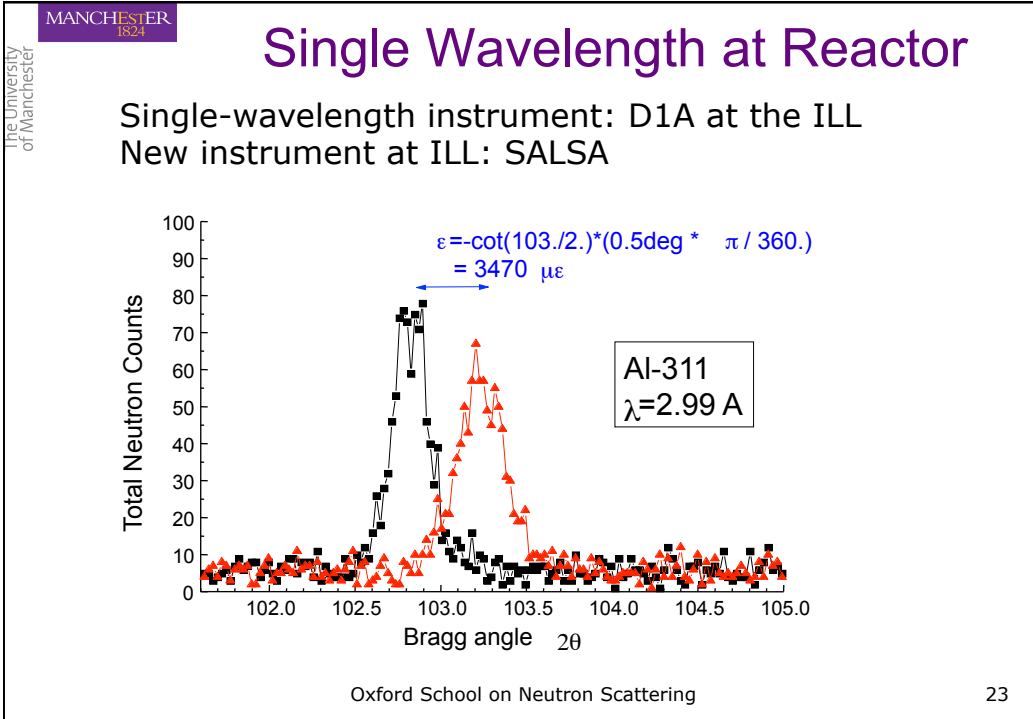
- Random Scattering length
- Penetration depth independent of energy/wavelength
- Electrically neutral
- Great penetration
- Low flux/intensity



Economic Depth	Al	Steel	Cu	Ti	Ni	SiC
mm	250	37	40	27	24	200



- Research Reactors**
- Fission in Reactor Core
 - Moderated neutrons
 - Monochromators in guide
 - **“Constant Wavelength”**
 - Many Facilities in Europe:
 - ILL, SINQ, FRM-2 (G), Petten (NL), ...
 - Generally low flux except ILL and FRM-2
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SALSA, ILL

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Typical Diffractometer at Synchrotron (here ID31 at the ESRF)

Detector

Sample Stage

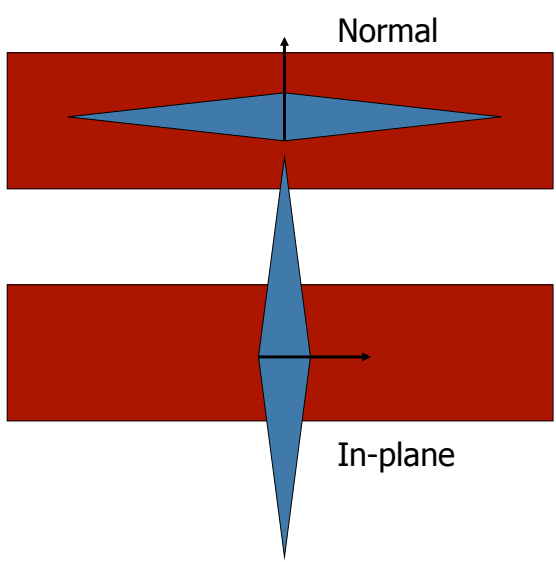
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Diamond gauge volume



Two orthogonal strain components sample different material volume

Analysers crystal for partly filled Gauge volume necessary!

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Time of flight method

- Sharp pulse leaves source
- High energy neutrons (short λ) travel faster and arrive first, low energy (long λ) last $\lambda = \frac{h}{mv}$ where l is the path length and t time of flight
- a single stationary detector records whole diffraction spectrum as a function of time of flight
- neutrons travel at $\sim 100\text{m/s}$ (speed of sound)
 - $\lambda = 2d \sin \theta$ with θ fixed, i.e. λ proportional to d

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Spallation Sources: Time of Flight

Detector

Neutron Pulse

Sample

Flight path L

Fast neutrons arrive earlier at detector!

$$\lambda = \frac{h}{p} = \frac{h}{mv} = \frac{ht}{mL}$$

$$+$$

$$\lambda = 2d \sin\theta$$

$$=$$

Time-of-Flight:

$$d = \frac{h}{2mL \sin\theta} t$$

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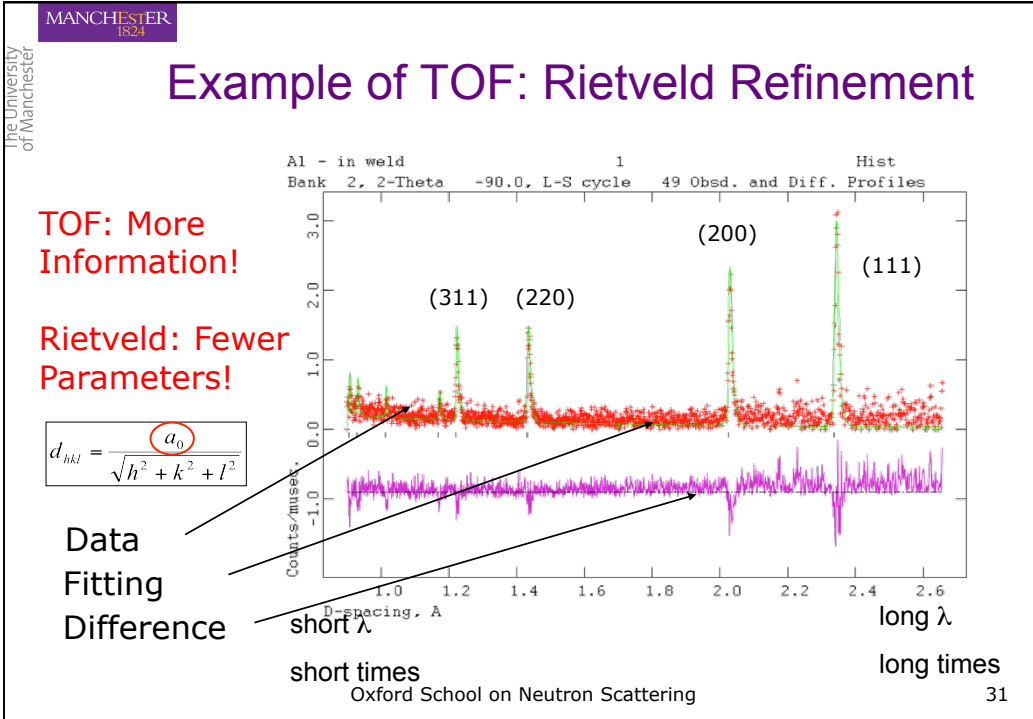
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ENGINE-X, ISIS

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Spallation Sources: Measurement of Strain

Strain: $\epsilon = \frac{a - a_0}{a_0} = \frac{\lambda - \lambda_0}{\lambda_0} = \frac{t - t_0}{t_0}$

Cubic gauge volume !

↑

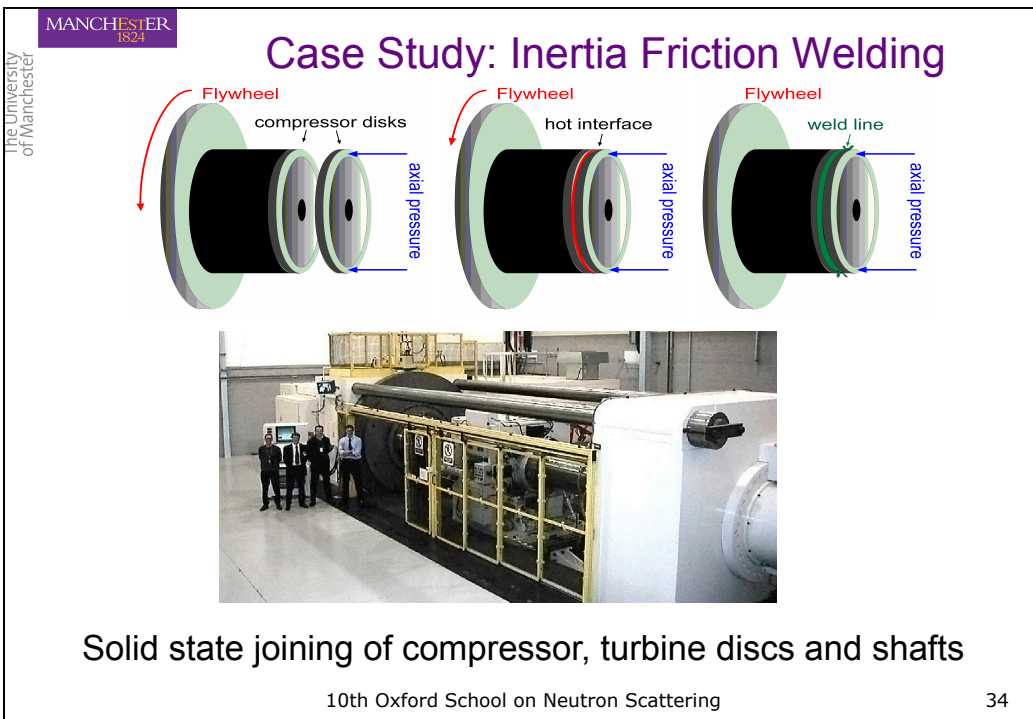
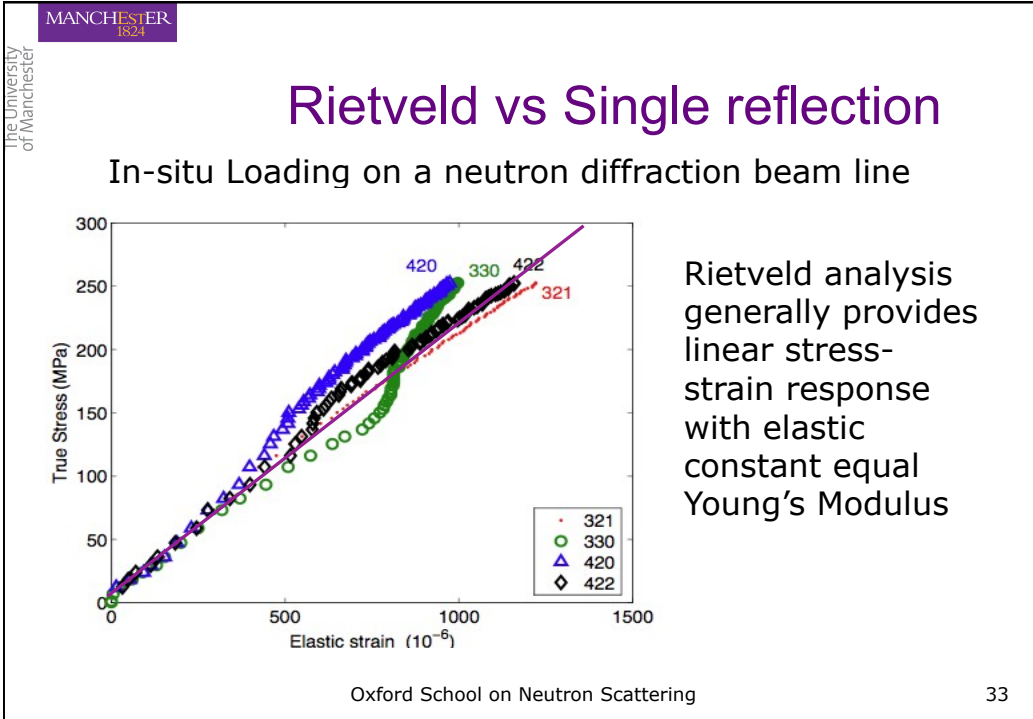
Time-of-Flight:

$$\lambda = \frac{h}{2mL \sin\theta} t$$

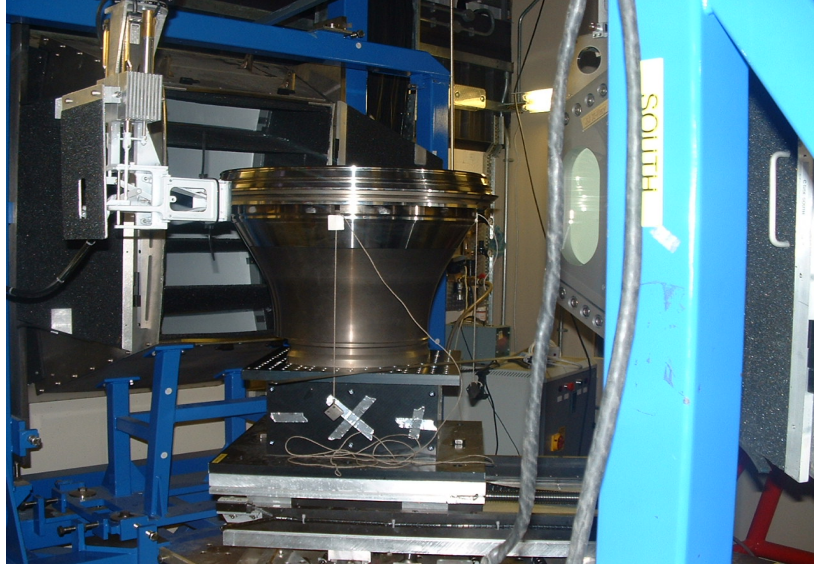
Fixed

ENGIN-X at ISIS

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Case Study: Inertia Friction Welding

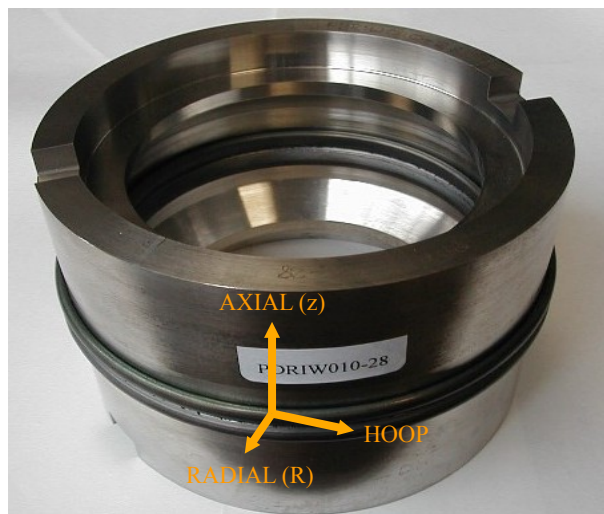


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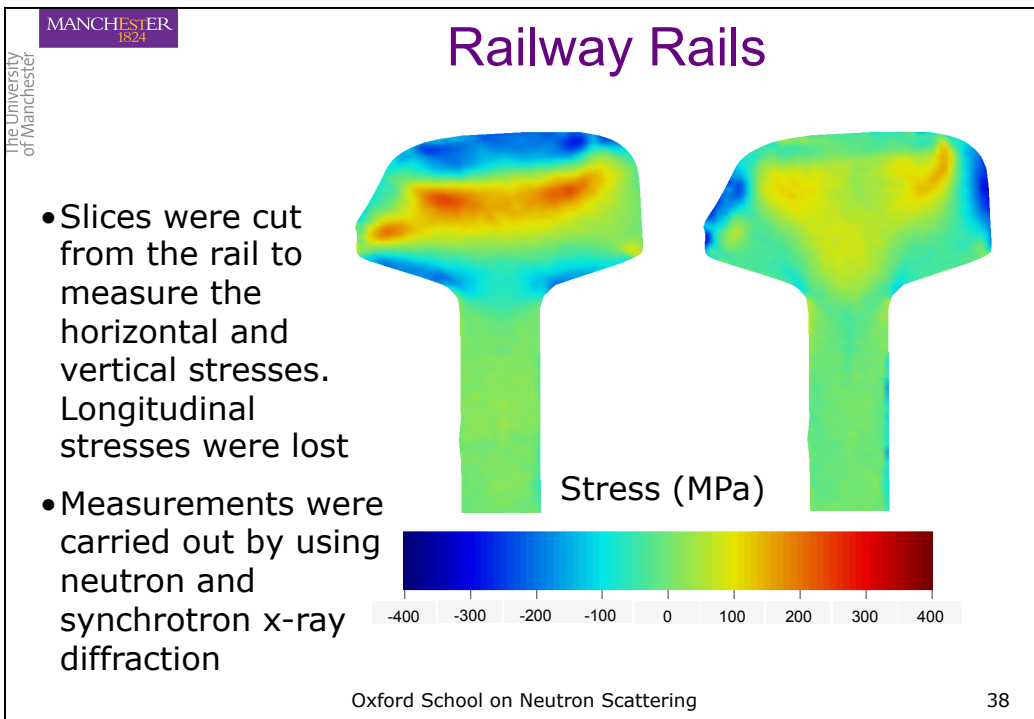
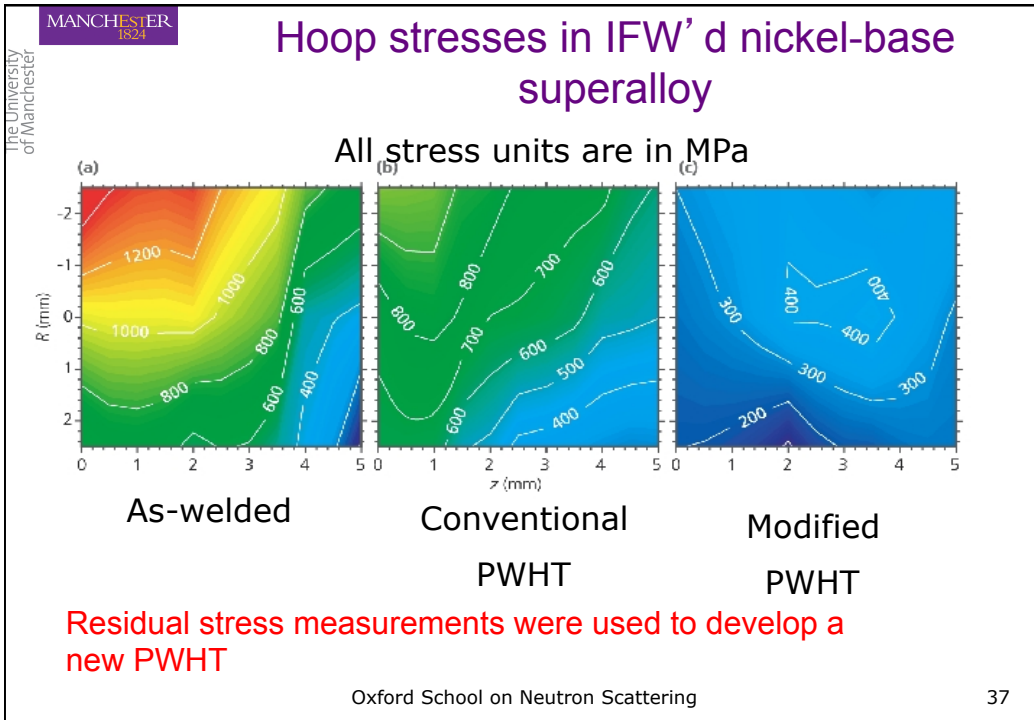
How would you measure such a sample ?

143mm diameter test inertia friction welds



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Case Study: Strain Mapping of a TIG weld

2D Map of Residual Strain about the End of a TIG Weld at 100 μ m Resolution

This map include 20,00 measurements and took 8 hours to acquire

Plot of 40mmx20mm area at end of TIG welded Al-2024

8mm wide TIG Weld in Aluminium Plate

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From Engineering to Physical/Mechanical Metallurgy

Single Crystal Anisotropy

Al, fcc

Single Crystal deformation

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What do we know ?

- Deformation of metallic materials happens along most densely packed plane in most densely packed direction
 - For example: in fcc it is the (111) plane and the $\langle 110 \rangle$ direction
- Relatively good understanding what happen when a single crystal is deformed

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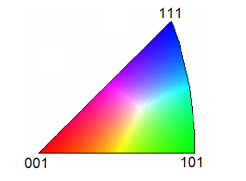
41

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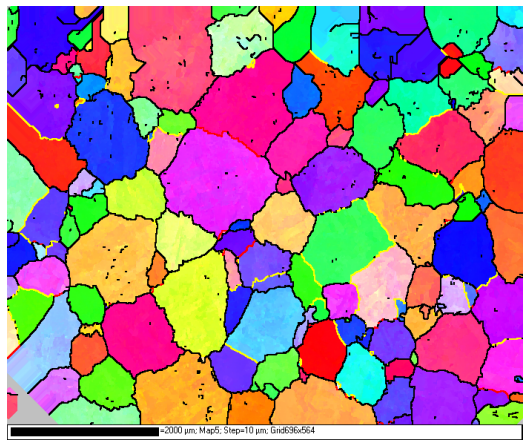
What we struggle with

- How does deformation work in a polycrystalline aggregate



001 111
101

β phase IPF colour key



=2000 μm; Map5; Step=10 μm; Grid636x564

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Deformation heterogeneity

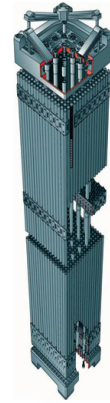
- Polycrystalline deformation is heterogeneous
- Single crystal elastic and plastic anisotropy
- Grain incompatibility during deformation results in intergranular stresses

Why do we care ?

- Deformation mechanisms play a crucial role when material is processed as it affects the microstructure and hence performance of the material that is generated
 - exactly the same alloy can have a strength of 300 or 1000 MPa just by changing the microstructure

Why do we care ?

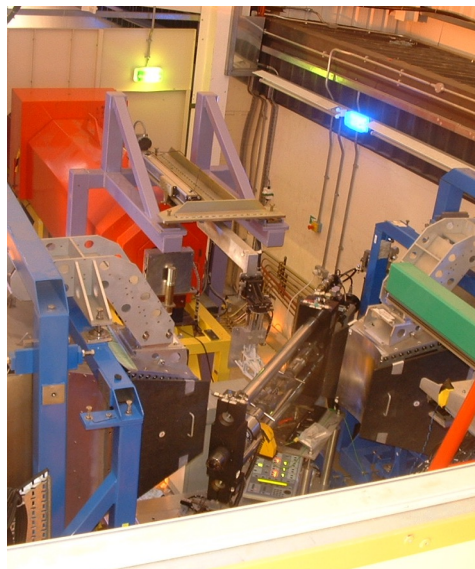
- Understanding deformation mechanisms is crucial in order to develop a more physical understanding of how materials perform
- Such knowledge is required to predict accurately the life of engineering components
- Particularly important for safety critical components



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In-situ loading experiments



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Experimental Methodologies

- Use of neutron diffraction and high energy synchrotron x-ray diffraction characterising residual stresses, intergranular strains and phase transformation

incident beam
Detector transverse direction
compression sample
Detector loading direction

longitudinal direction
transverse direction

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Case Study – Ni base Superalloy

- Use of neutron diffraction and high energy synchrotron x-ray diffraction characterising residual stresses, intergranular strains and phase transformation

Example – Ni base Superalloy

1.
2.
 $l_1 = l_2$

Dislocation
 L
 $L - 2r$
 $L - 2r$

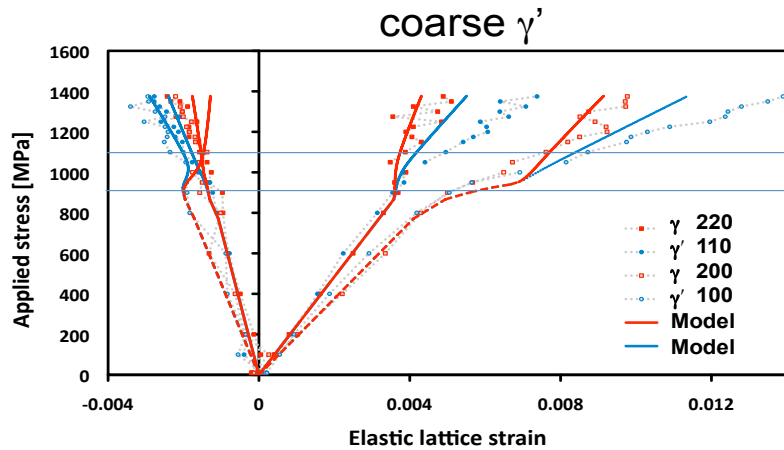
Applied stress
Elastic lattice strain

a) b)

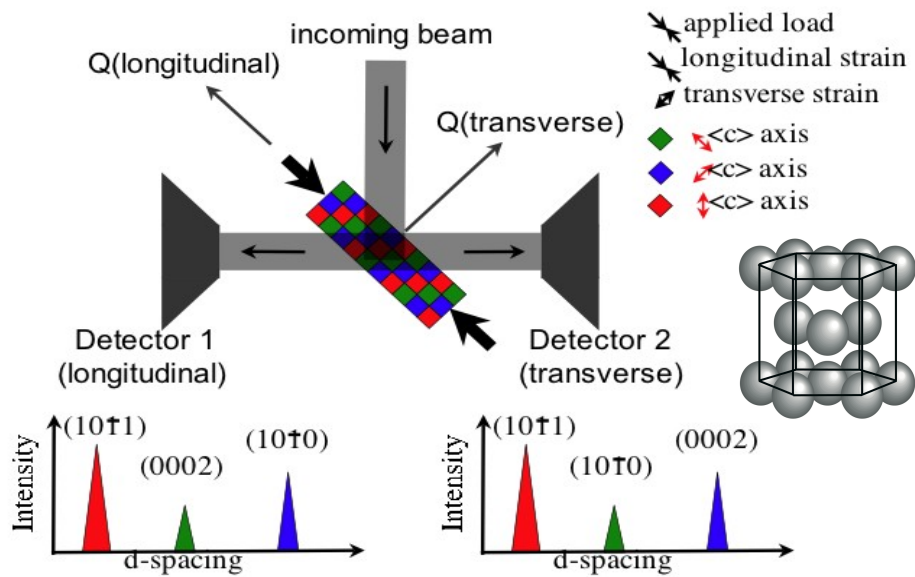
Blue: elastic strain response of γ'
Red: elastic strain response of γ

Case Study – Ni base Superalloy

- Use of neutron diffraction and high energy synchrotron x-ray diffraction characterising residual stresses, intergranular strains and phase transformation

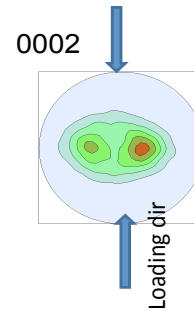
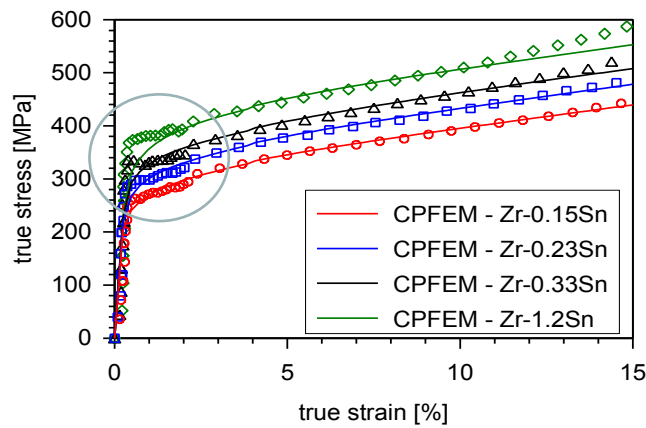


Case Study – hcp metal

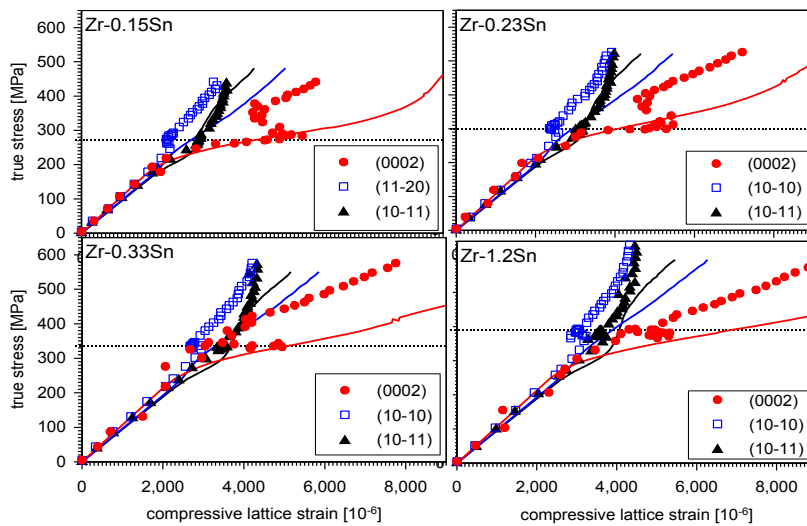


Effect of Sn on twinning in Zr alloys

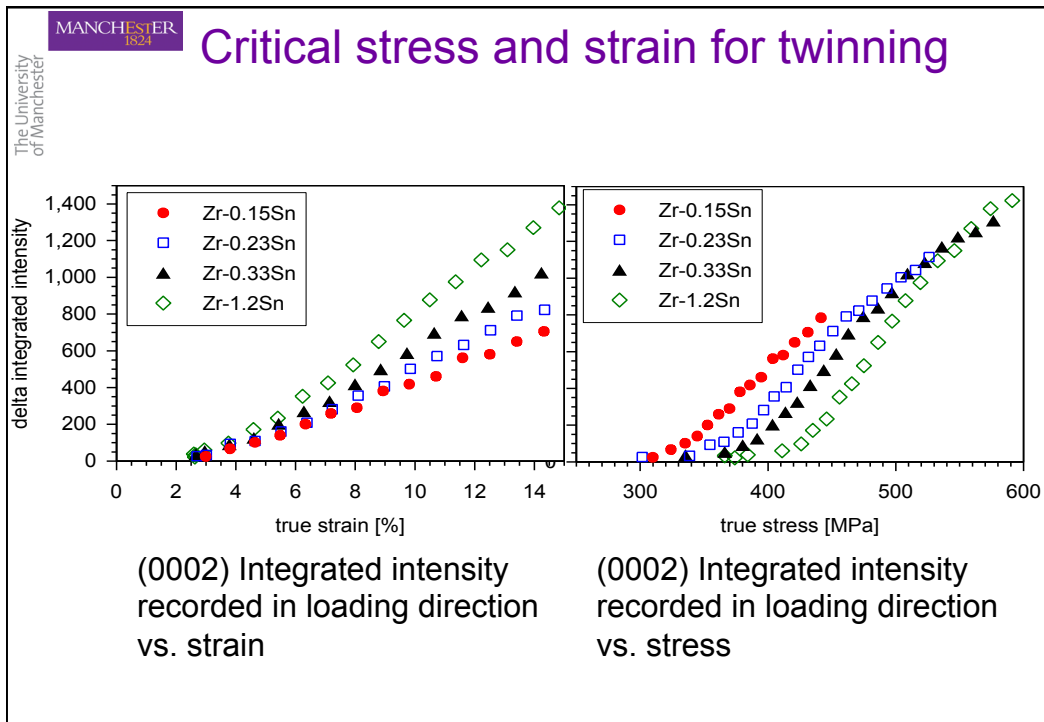
- Twin nucleation criteria unknown
- Role of alloying elements on twinning unknown



Role of Sn on intergranular strain development



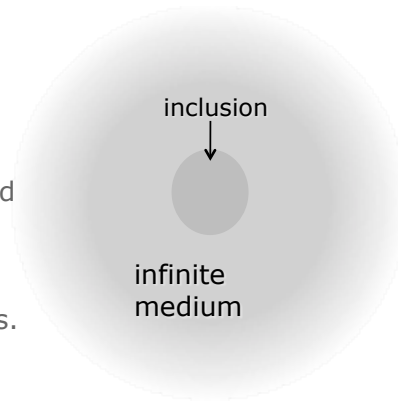
Lattice strain recorded in the loading direction



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- ## Modelling deformation
- **Micromechanics**
 - Dislocations, particles, grain boundaries (grain size), interstitial atoms
 - **Continuum mechanics:**
 - Stresses and strains
 - Intergranular stresses
 - **Polycrystal plasticity**
 - Mean field methods, i.e. every grain has the same matrix
 - Finite element methods
 - Each grain has a characteristic neighbourhood
 - Predict maximum and minimum stresses ?
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EPSC Modelling

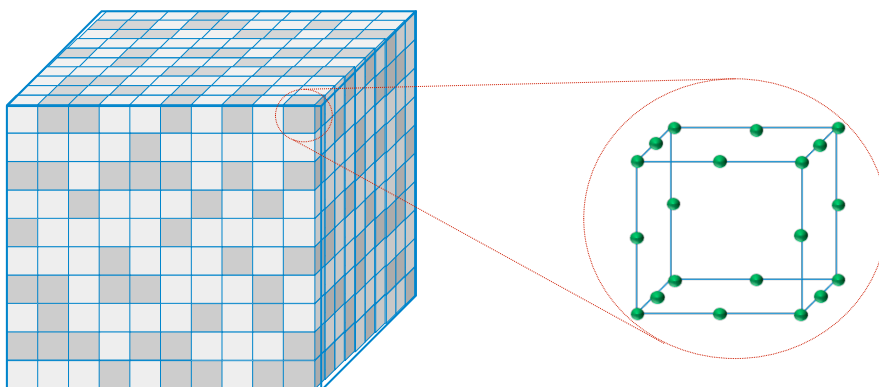
- The elasto-plastic self-consistent model (EPSC), is based on the Eshelby-Hill formulation.
- An elliptical inclusion in an infinite medium.
- The surrounding medium is the average of all orientations.
- The inclusion has uniform stress and anisotropic properties i.e. different orientations have different elastic moduli and plastic deformation is only allowed on specified slip planes.
- The model is capable of simulating multiple thermo-mechanical processes.



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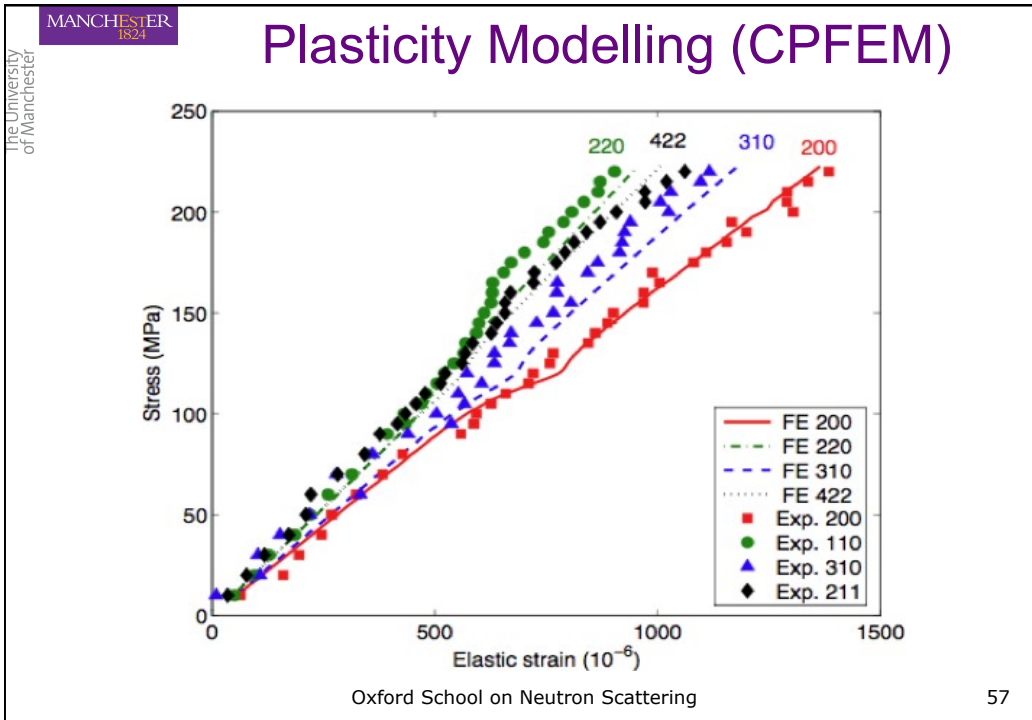
CPFEM

- CPFEM is more computer intensive than EPSC modelling, however, it enables the simulation of specified grain structures.



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Attempted General Guidelines: Neutrons

Neutrons:

- Non-destructive, full stress analysis because of cubic Gauge Volume (think three directions)
- Good penetration depth due to neutrality
- Big bulky sample with low stress gradients
- Reasonable spatial resolution independent of atomic number
- Steels, aluminium, nickel, copper zinc or related
- Sample in harsh environment: furnace, cryo. etc.
- Phase analysis with Rietveld analysis

Not-so good: near surface or thin materials, titanium, boron cadmium, fast, high-spatial resolution, high instrumental resolution, hydrogenous materials

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Attempted General Guidelines: Synchrotrons

Synchrotrons:

- Non-destructive, fast strain mapping, mostly single peak
- Light alloys (small atomic number)
- High spatial resolution aluminium-titanium (think microns)
- High instrumental resolution (small peak width)
- Near surface measurement because of analyser crystal
- Bulk materials / larger atomic number with energy-dispersive method
- Polymers

Not so good at: Steels and higher, big bulky samples, harsh environments, diamond shaped GV